

Global Near Real-Time MODIS-based Flood Mapping: Upcoming Improvements and Transition to LANCE

NDRC Webinar

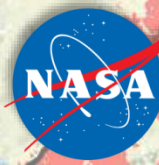
1 April 2020

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Co-Is: Bob Brakenridge, Albert Kettner: Dartmouth Flood Observatory,
University of Colorado



Goddard Space Flight Center



Dartmouth
Flood Observatory

SE Asia flooding – Oct 2011

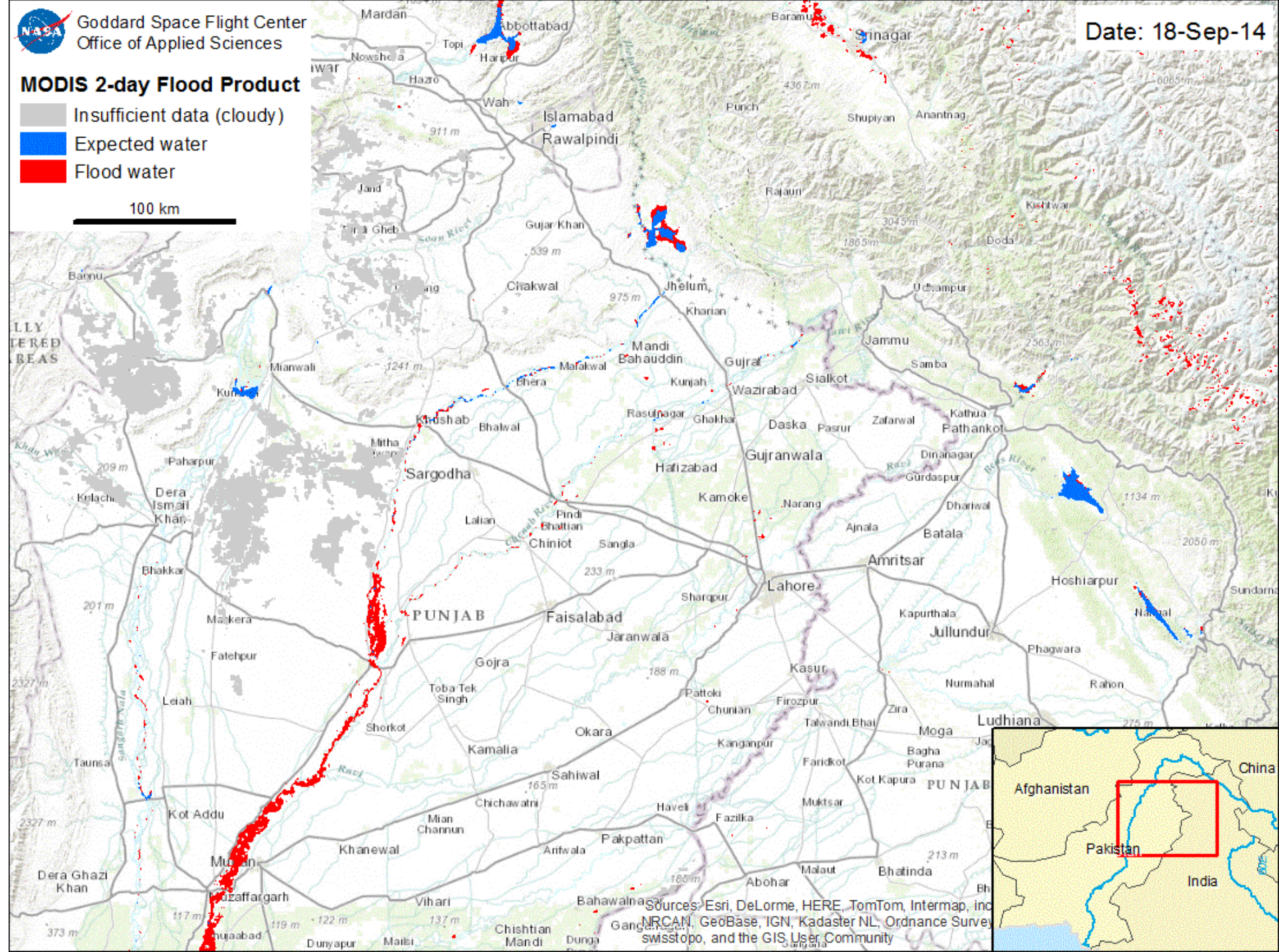


Indus Flooding Sept 2014

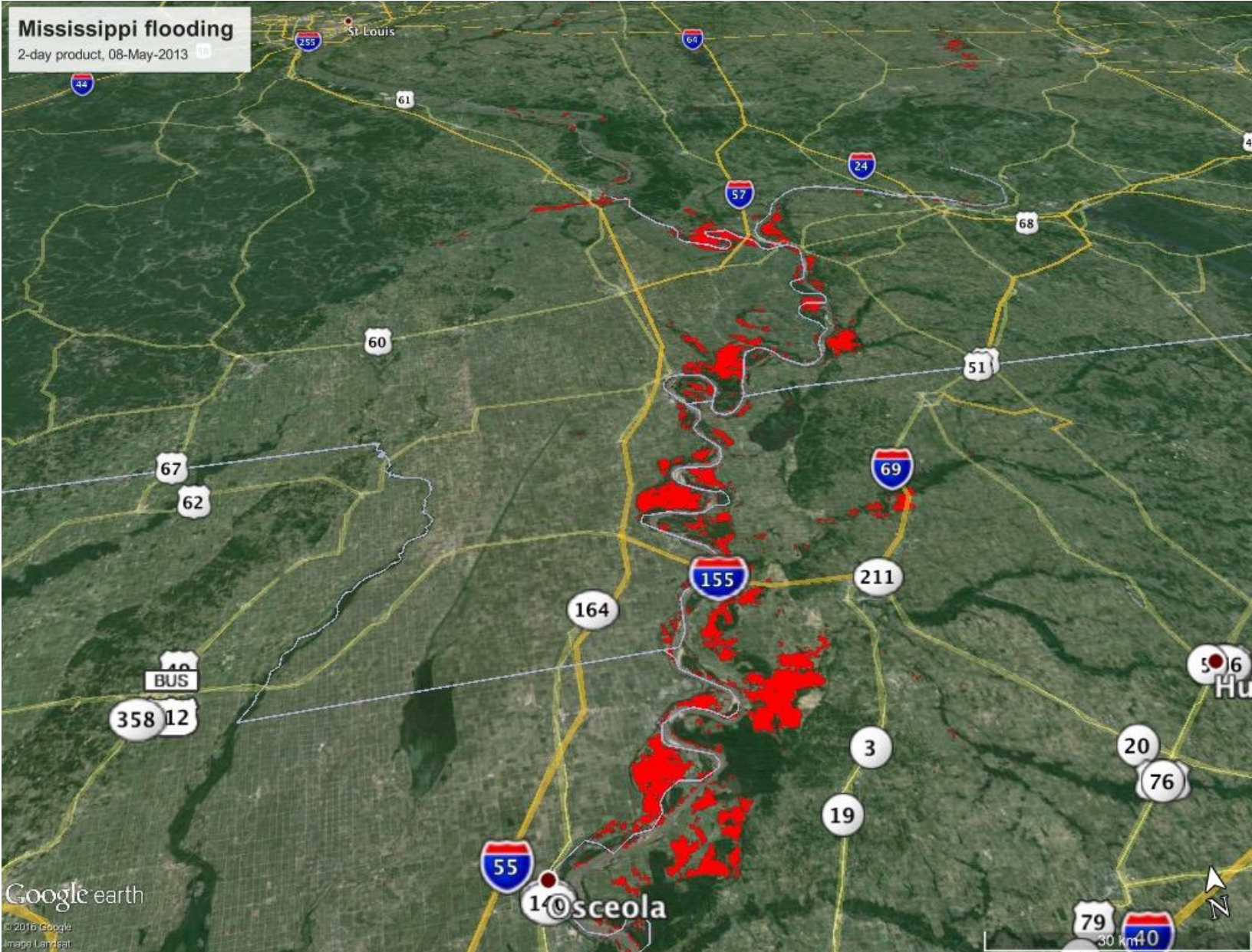
MODIS 2-day Flood Product

- Insufficient data (cloudy)
- Expected water
- Flood water

100 km



Mississippi river flooding – May 2013





Selection of end users



Satellite-detected Waters



World Food Program



unitar
United Nations Institute for Training and Research

UNOSAT

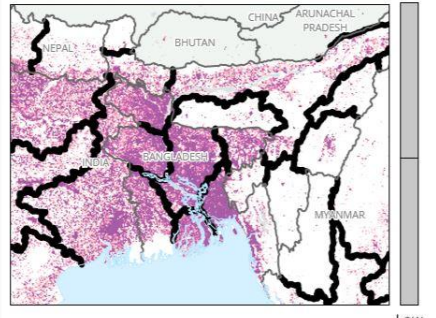


Situation Overview
Satellite-detected waters

The dashboard shows a 3-days composite product - elaborated by NASA within the Near Real Time (NRT) Global Flood Mapping project - showing the satellite detected waters (18 July 2019) in Nepal, eastern India, Bangladesh and Myanmar.



Population density



Accumulated rainfall (12 - 18 July, mm)



FEMA

NRCC – National Response Coordination Center

SAVING LIVES CHANGING LIVES



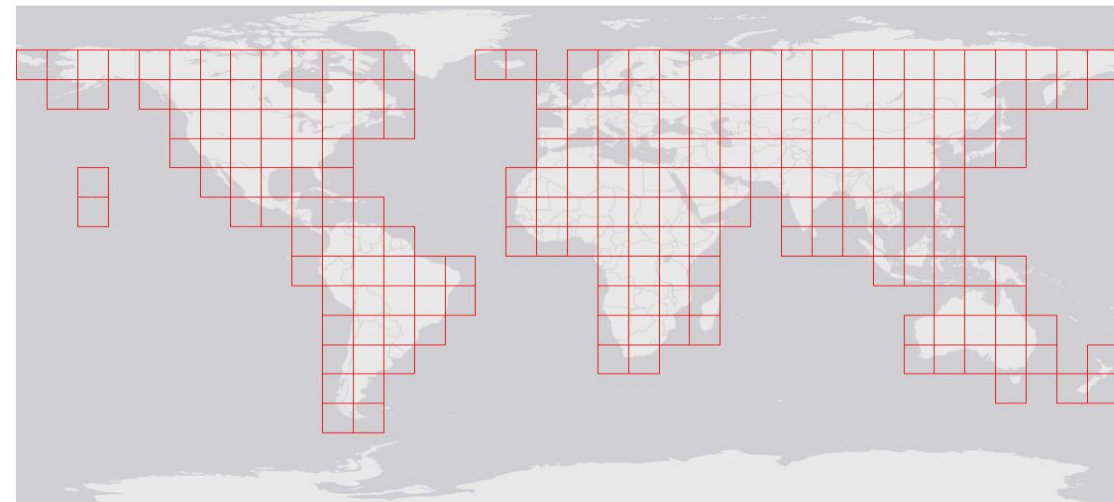
- Country Office
- Field Office
- Sub Office
- National Capital
- Major Town
- Intermediate Town
- Small Town
- Village
- International boundaries
- Coastline
- Province boundaries
- River
- Surface waterbodies

Satellite waters (source: NASA)

MODIS_binary_.tif
Value
0 ≤ 1

A brief history

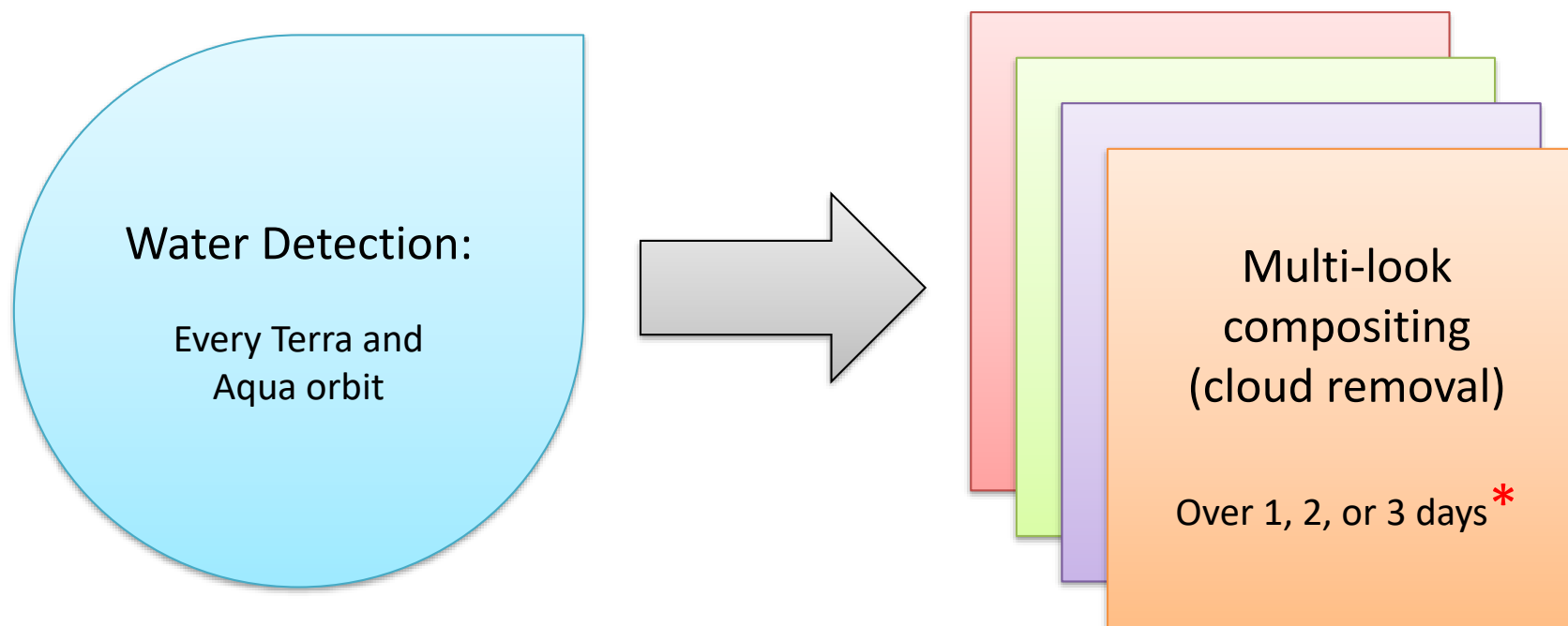
- Early 2000s: Bob Brakenridge (Dartmouth Flood Observatory): manual generation of flood maps using MODIS rapid response imagery as source
- Generally effective, but:
 - Not automated!
 - Used rapid response jpegs not intended for data analysis
- ~ 2010, NASA GSFC's Office of Applied Science initiated a project to automate production
 - Using LANCE-generated NRT surface reflectance
 - Automated global flood map production began 2012:
 - 223 10x10° tiles x 3 products (2-day, 3-day, 14-day) = 669 daily product suites generated.
 - Typically available within 6 hours of Aqua overpass (~ 8:00 PM local time).
 - Now transitioning full production into LANCE



Current Status

- LANCE transition nearly complete....mid 2020?
 - Has required a complete rewrite of code running on PI-owned server: from a combination of IDL/ENVI, python, and perl, to perl and PDL (Perl Data Language).
 - Code architecture updated and simplified, but requires some new approaches to production rules in LANCE/MODAPS for the multi-day compositing.
- Other benefits to LANCE transition
 - Reduced latency of product generation; can process as soon as incoming granules are available. (previously scheduled at ~8pm local time).
 - Add needed improvements: updated reference water, “recurring flood”, improved masking
 - Product browseable within ESDIS/Worldview interface – much more powerful end-user experience
 - Possible back-processing of MODIS archive, providing ~20 year history of earth surface water dynamics at 250m resolution

Approach: two key steps



* Depends on cloud cover at site of interest

Approach: in more detail

1. Water Detection

- Apply algorithm to all incoming MOD09 (surface reflectance) swath data granules

2. Multi-look compositing

- Require multiple water observations to mark a pixel as water (generally)

3. False-positive masking

- Remove likely cloud-shadow and terrain-shadow false positives

4. Determination of flood

- Compare detected water to reference of permanent water (lakes, rivers), and to recurring flood areas, to provide a product showing:
 1. Surface water (= expected water)
 2. ***NEW in LANCE*** Recurring flood (= flood occurring in areas where frequently previously detected)
 3. Flood (= flood occurring in areas where not frequently previously detected)
 4. Insufficient data (clouds, NODATA, etc) (= potential false negatives)

Multi-look compositing example

SE Asia Floods 2011

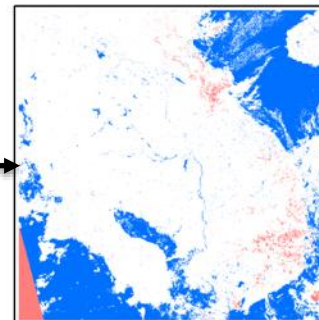
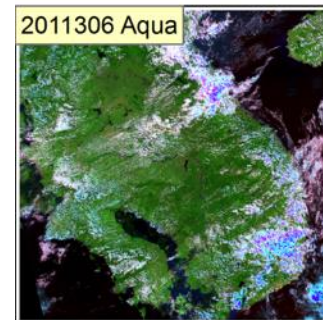
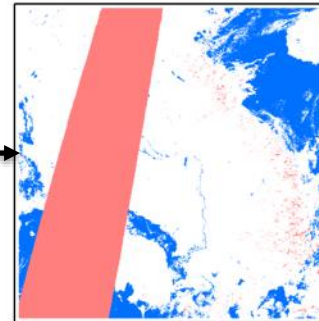
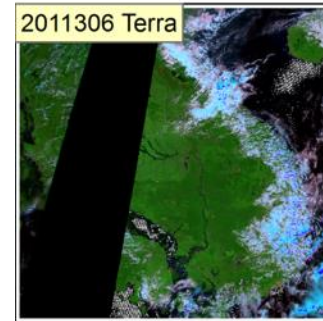
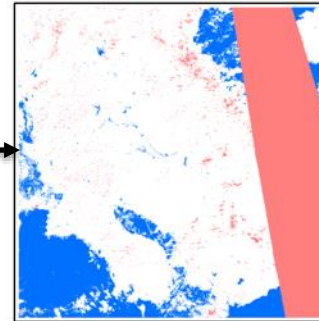
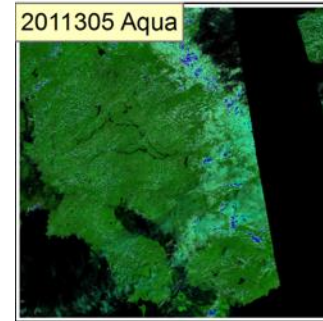
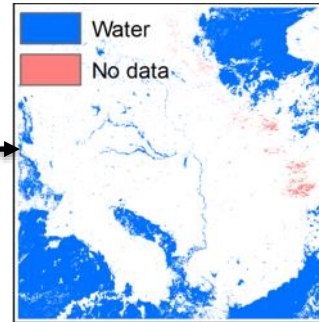
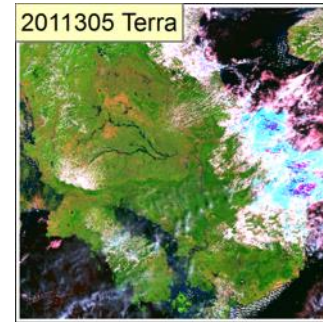
Tile: 100E020N

Dates: 1-2 Nov 2011

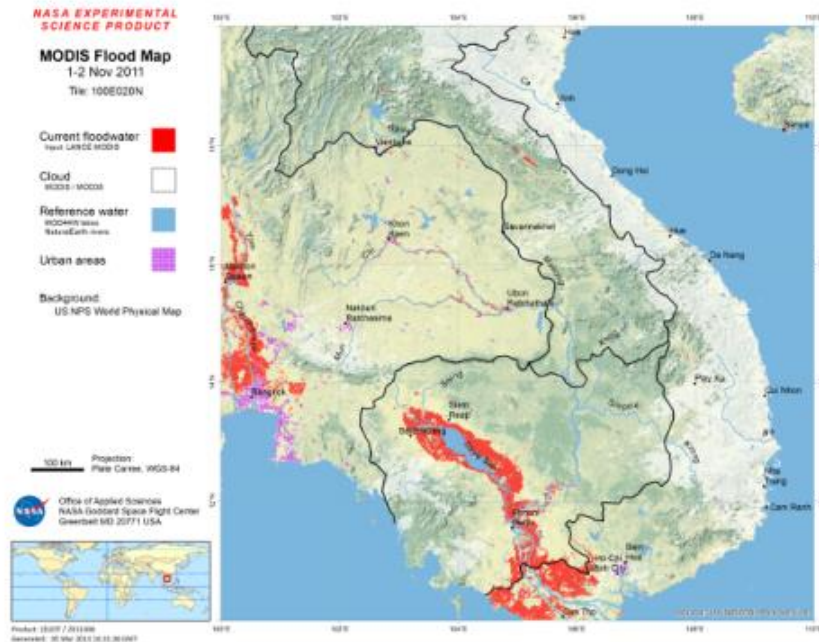
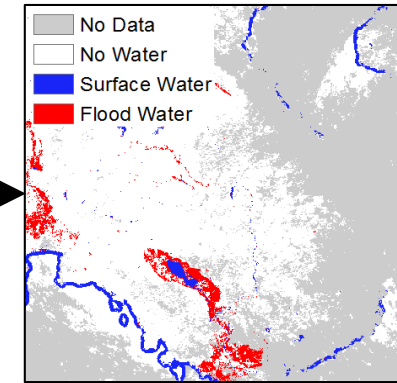
Composite: 2D2O = 2-day 2-obs.

Input MOD09 721

Water Detection



2-day Product



1. Water Detection: Input data

LANCE NRT MODIS Surface Reflectance product (MOD09):

- Daily Terra and Aqua SR bands 1, 2 (250 m) and band 7 (sharpened to 250 m)
 - Used in core water detection algorithm.
- Cloud mask flag (from MOD09 QA State Layer)
 - Informs when we cannot see the surface; NODATA (really: no SURFACE data)
 - Pre-LANCE: used MOD35 cloud product
- Cloud shadow flag (from MOD09 QA State layer)
 - Assists with removal of cloud-shadow false-positives.
 - Pre-LANCE: used MOD06 / Atmosphere and geometrically projected clouds from MOD35

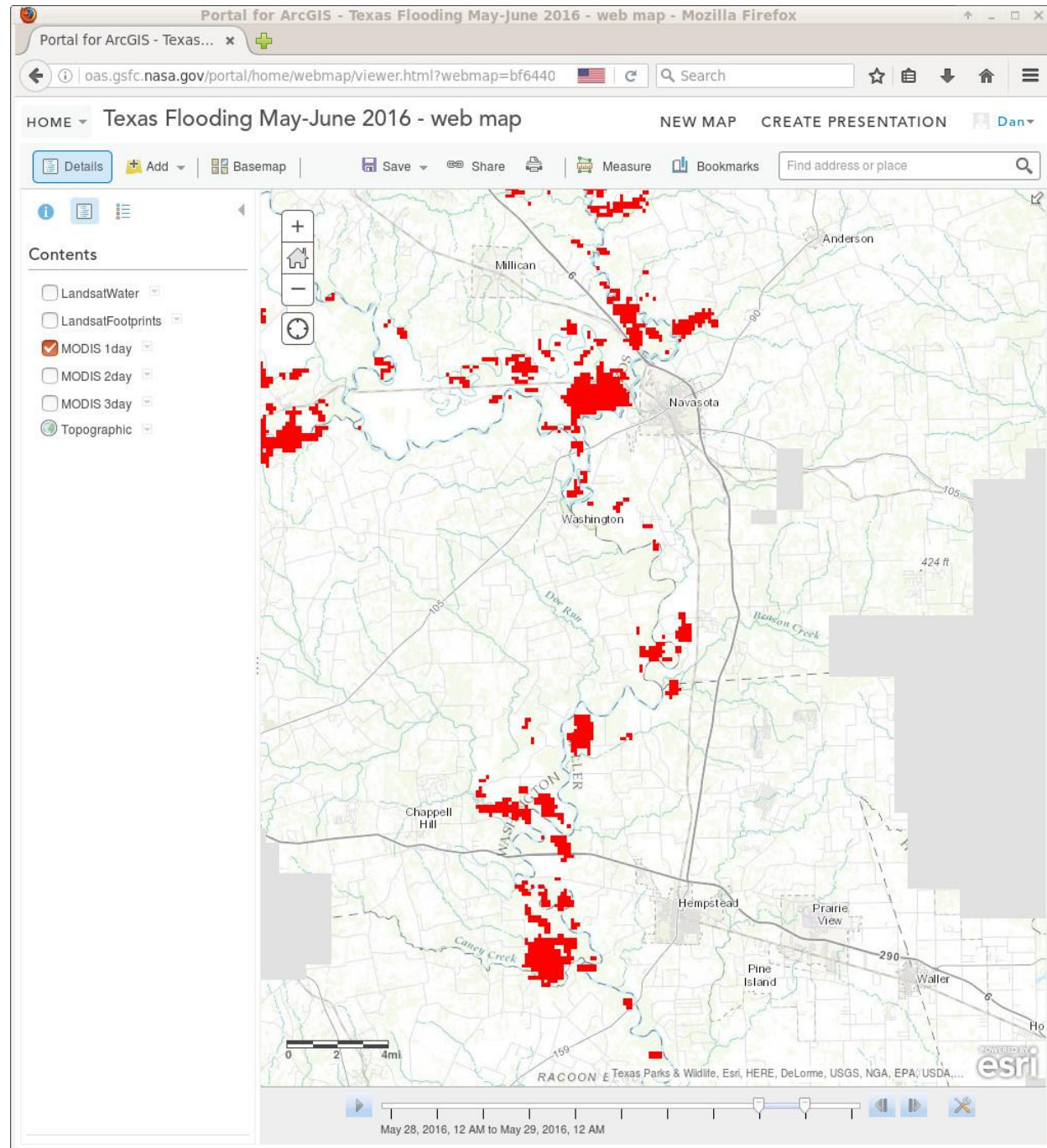
2. Multi-look compositing

- 2-day **standard product** (2D2O): Requires 2 water observations over 2 days (potentially 4 observations).
- 3-day product (3D3O): Requires 3 water obs over 3 days. Minimal false-positives. Potentially less current.
- 1-day product (1D1O): Requires JUST 1 observation over 1 day.
 - Most current, but **WILL contain cloud-shadow false-positives IF cloud is present.**
- Which to use? It depends on cloud conditions, and:
 - Tolerance for false positives (and false negatives).
 - Need for only the most up-to-date information.
- Clear conditions? (Can verify visually in Worldview app: <https://worldview.earthdata.nasa.gov/>) Use 1-day.
- Very sensitive to false-positives and/or currency is not critical? Use 3-day.
- Need the latest info? Use 1-day, but you **MUST** check cloud cover!
- Best approach? Review all products, check cloud cover, and evaluate for given event and needs.

Impact of composite period:

1-day product

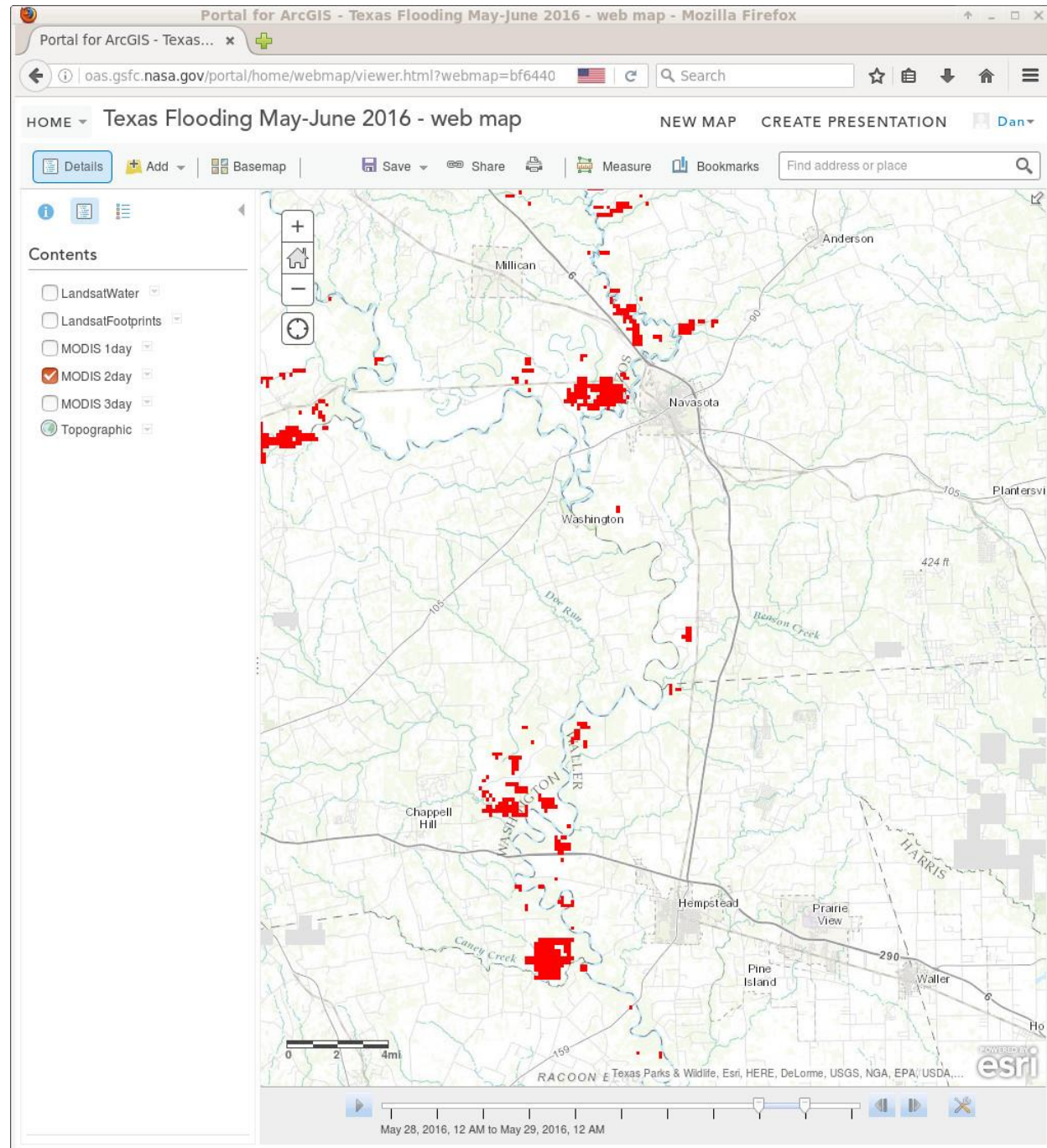
Houston-area flooding June 2016



Impact of composite period:

2-day product

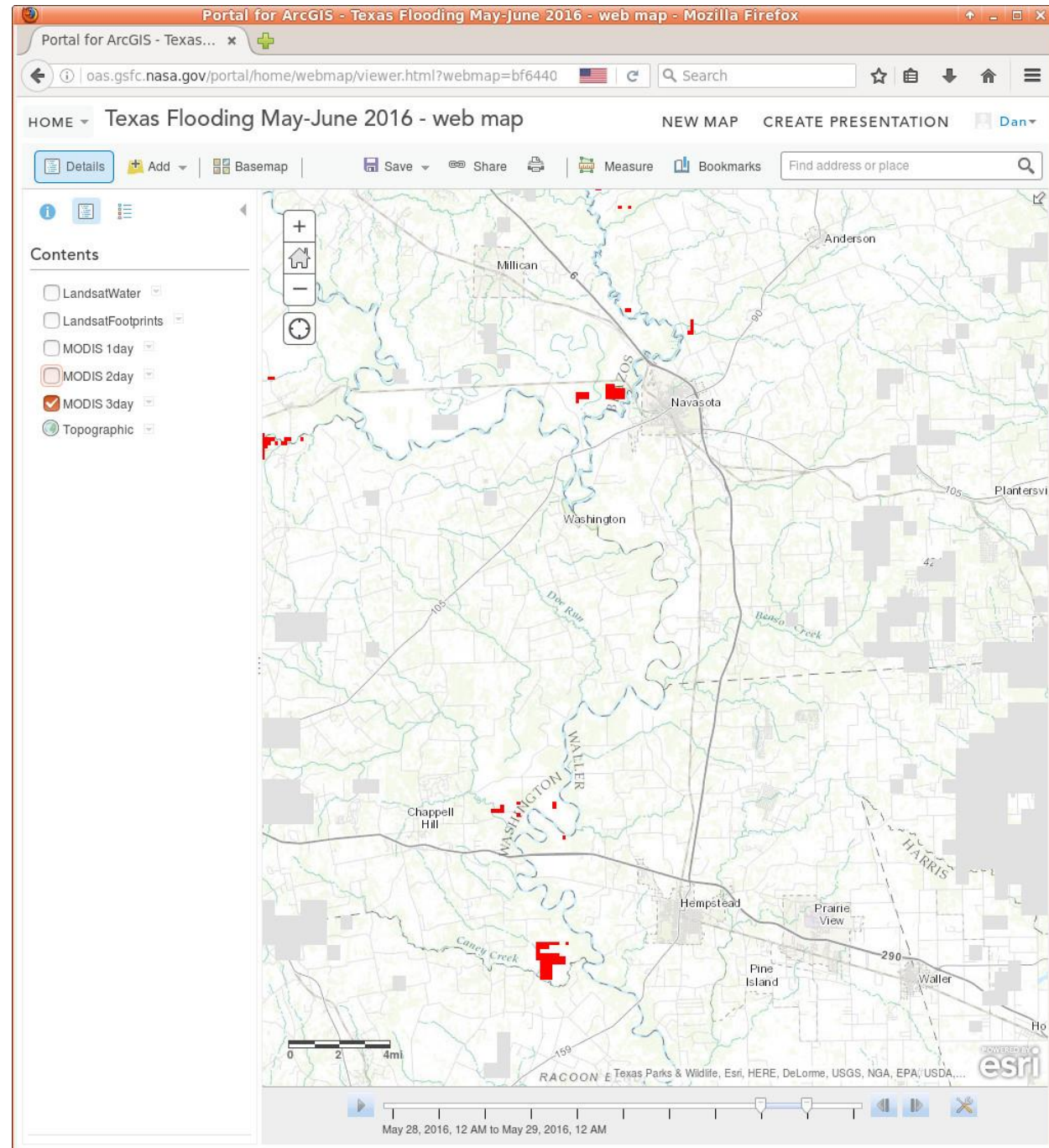
Less flood shown → cloud preventing multiple water observations



Impact of composite period:

3-day product

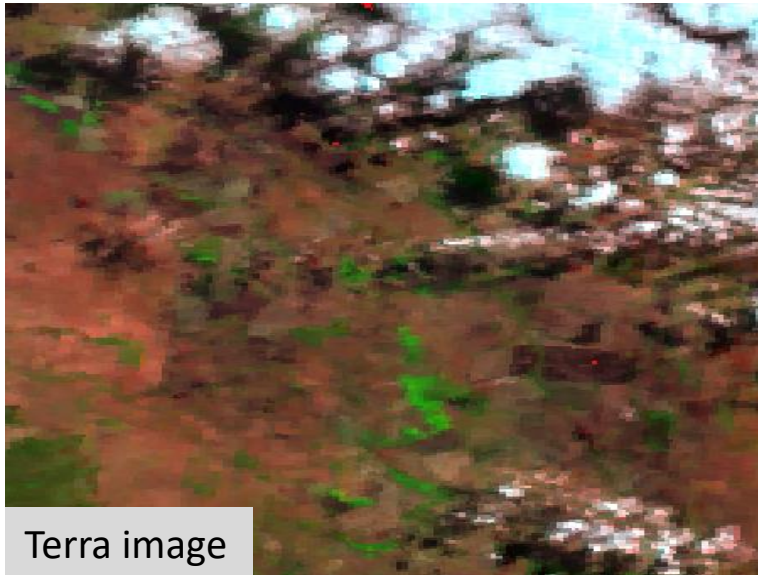
Even less flood shown → not helpful



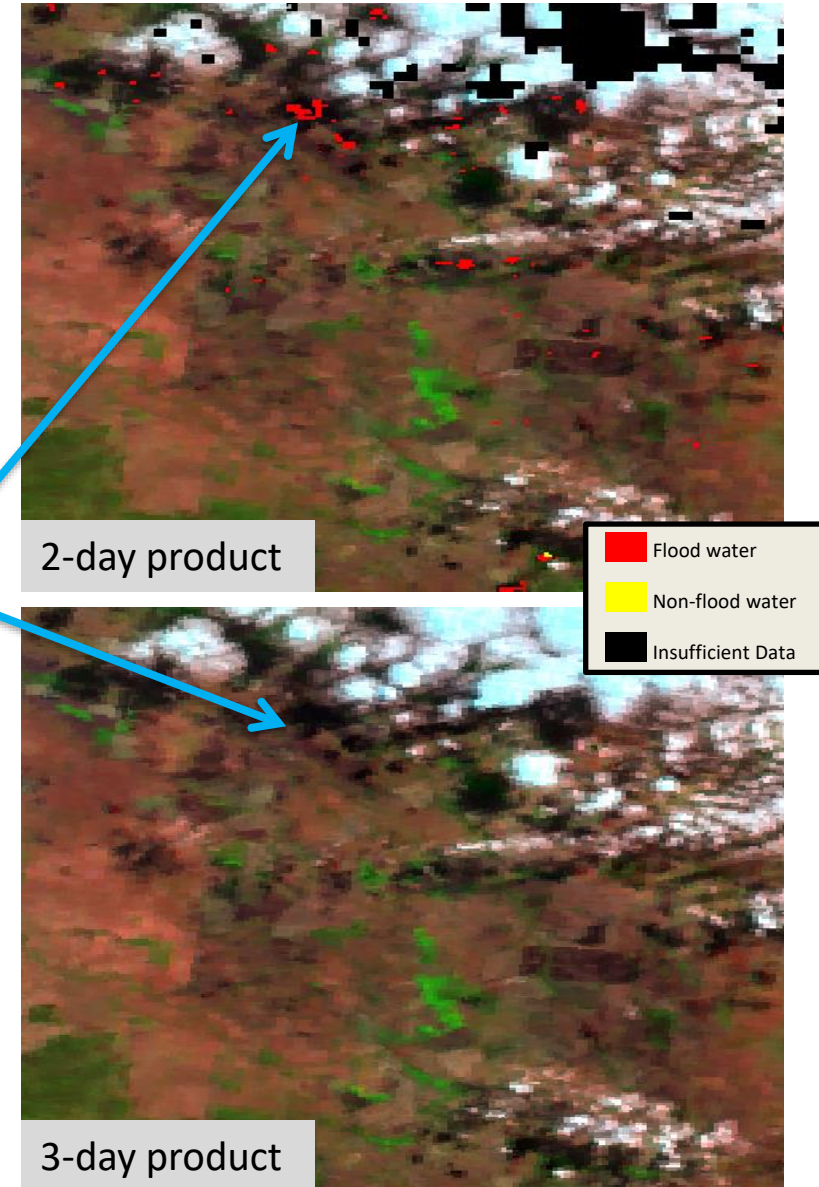
Impact of composite period

Cloud-shadow removal: 2 vs 3-day product

→ 3-day is better



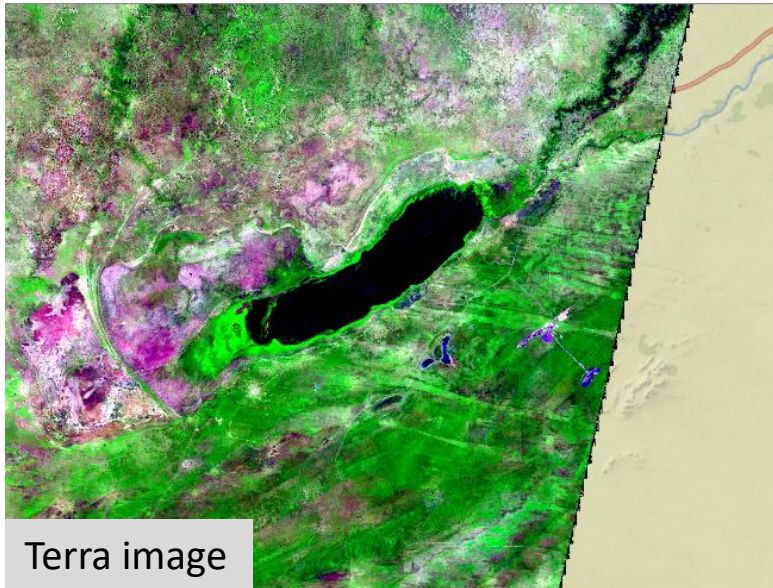
3-day product removes
cloud shadow false-positives
persisting in 2-day product



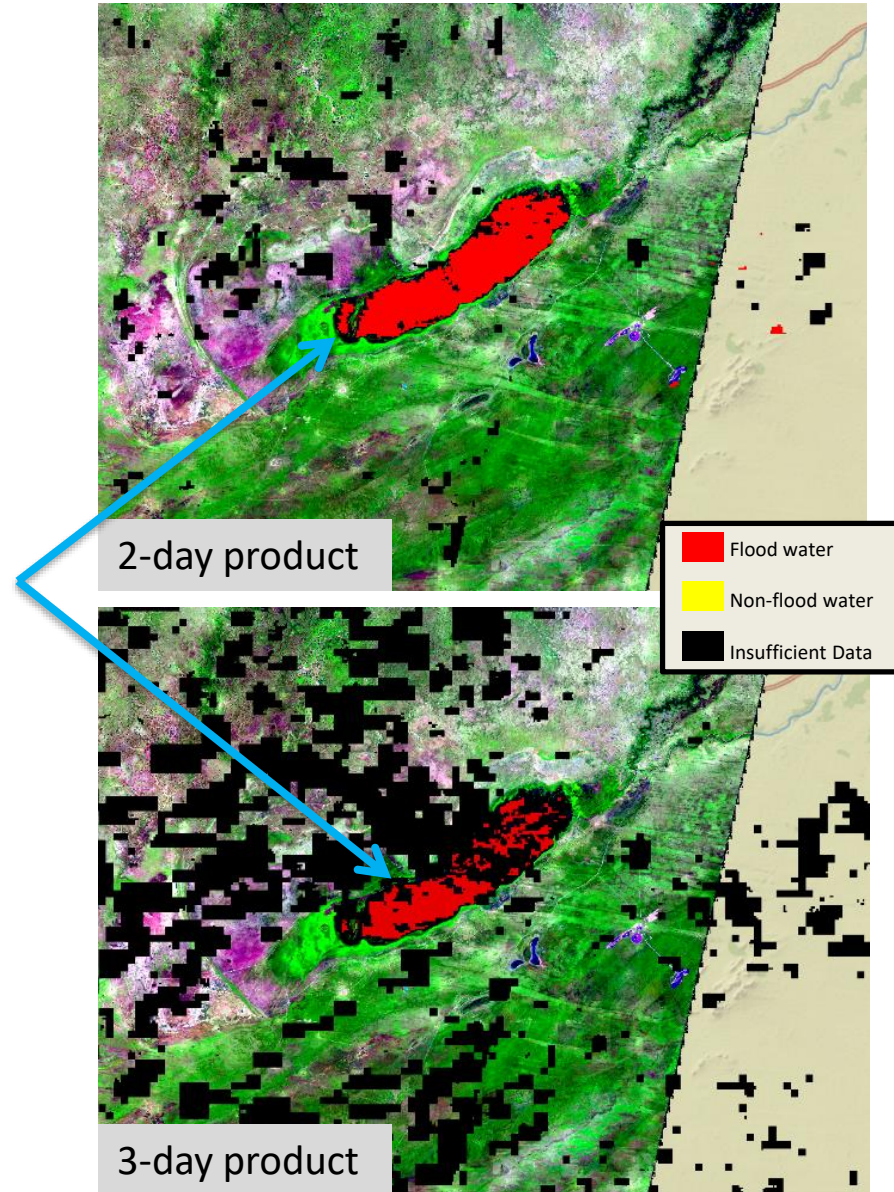
Impact of composite period

Cloud-shadow removal: 2 vs 3-day product

→ 2-day is better



2-day shows better coverage of
flood zone;
3-day patchy due to cloudiness

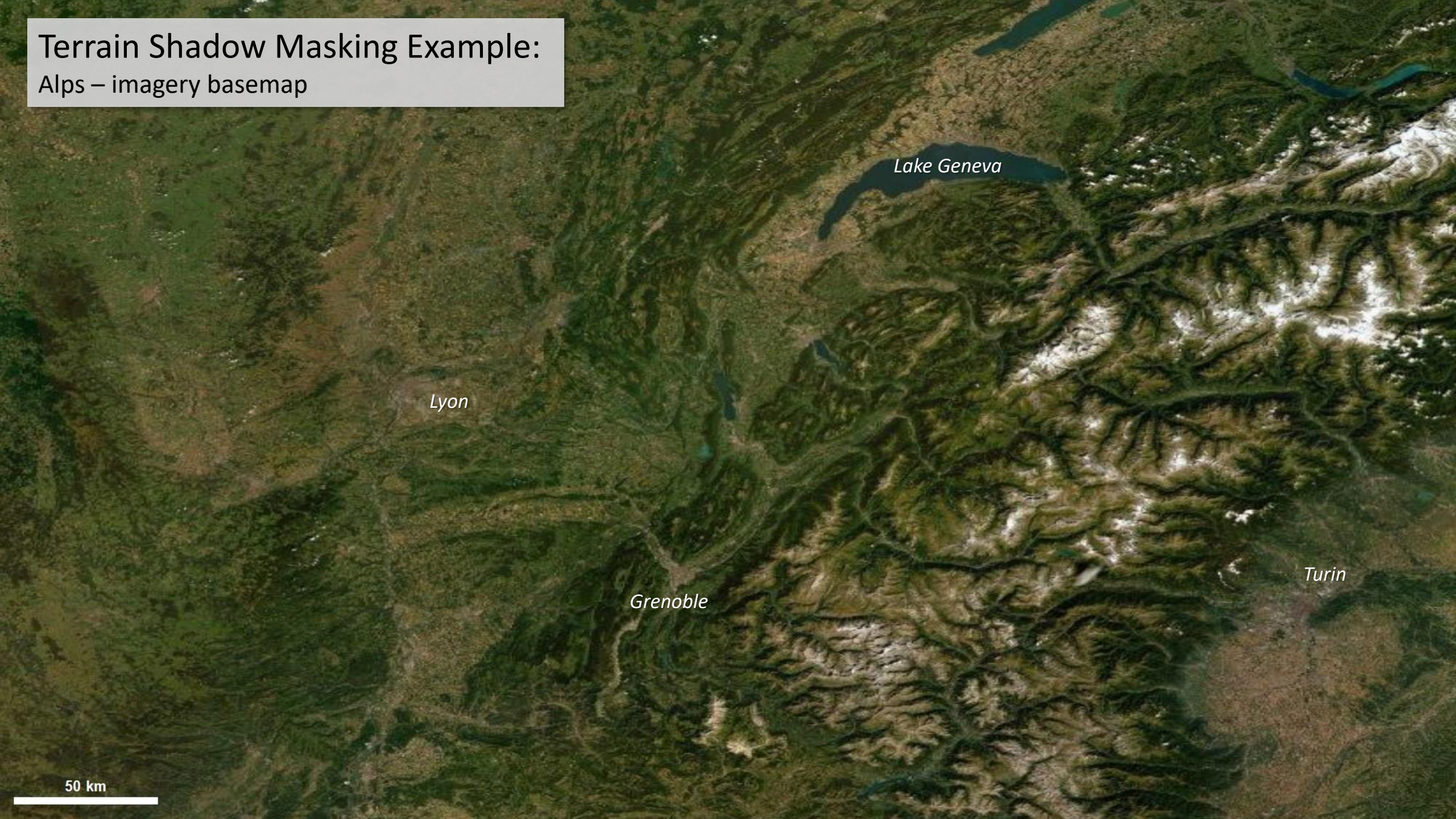


3. False-positive masking

- Shadows look like water!
- Terrain shadows
 - In mountainous areas, mostly in winter
 - To filter, we use pre-computed shadows (good but not perfect)
 - New – apply HAND topographic mask
- Cloud shadows
 - Multi-look compositing mostly eliminates
 - For 1-day, we apply the cloud shadow mask included in MOD09 product
 - Imperfect, but helpful

Terrain Shadow Masking Example:

Alps – imagery basemap



Lake Geneva

Lyon

Grenoble

Turin

50 km

Example: Alps - terrain



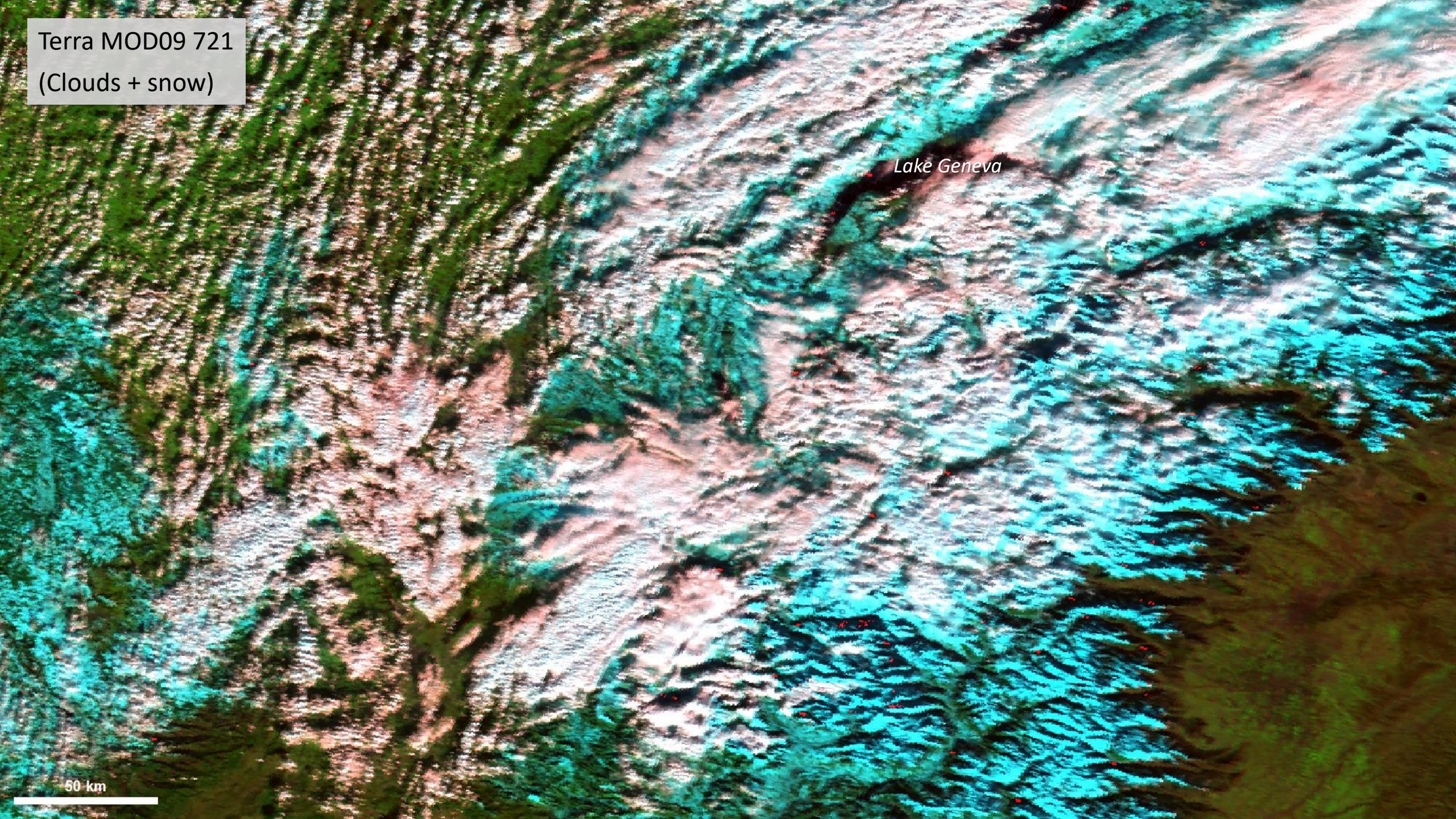
Lake Geneva

Grenoble

Terra MOD09 721
(Clouds + snow)

Lake Geneva

50 km



Terra MOD09 721
+ Water detections

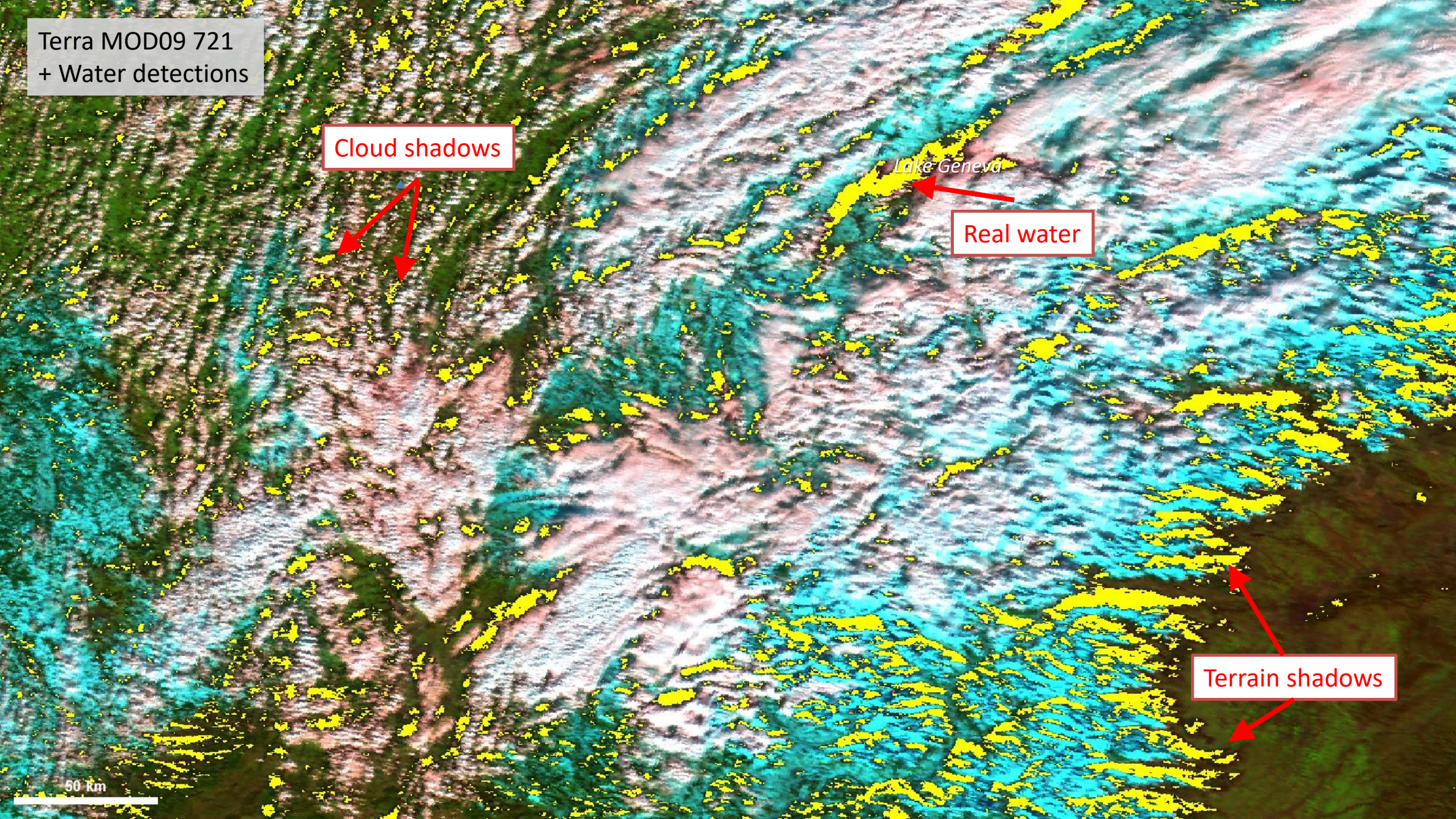
Cloud shadows

Lake Geneva

Real water

Terrain shadows

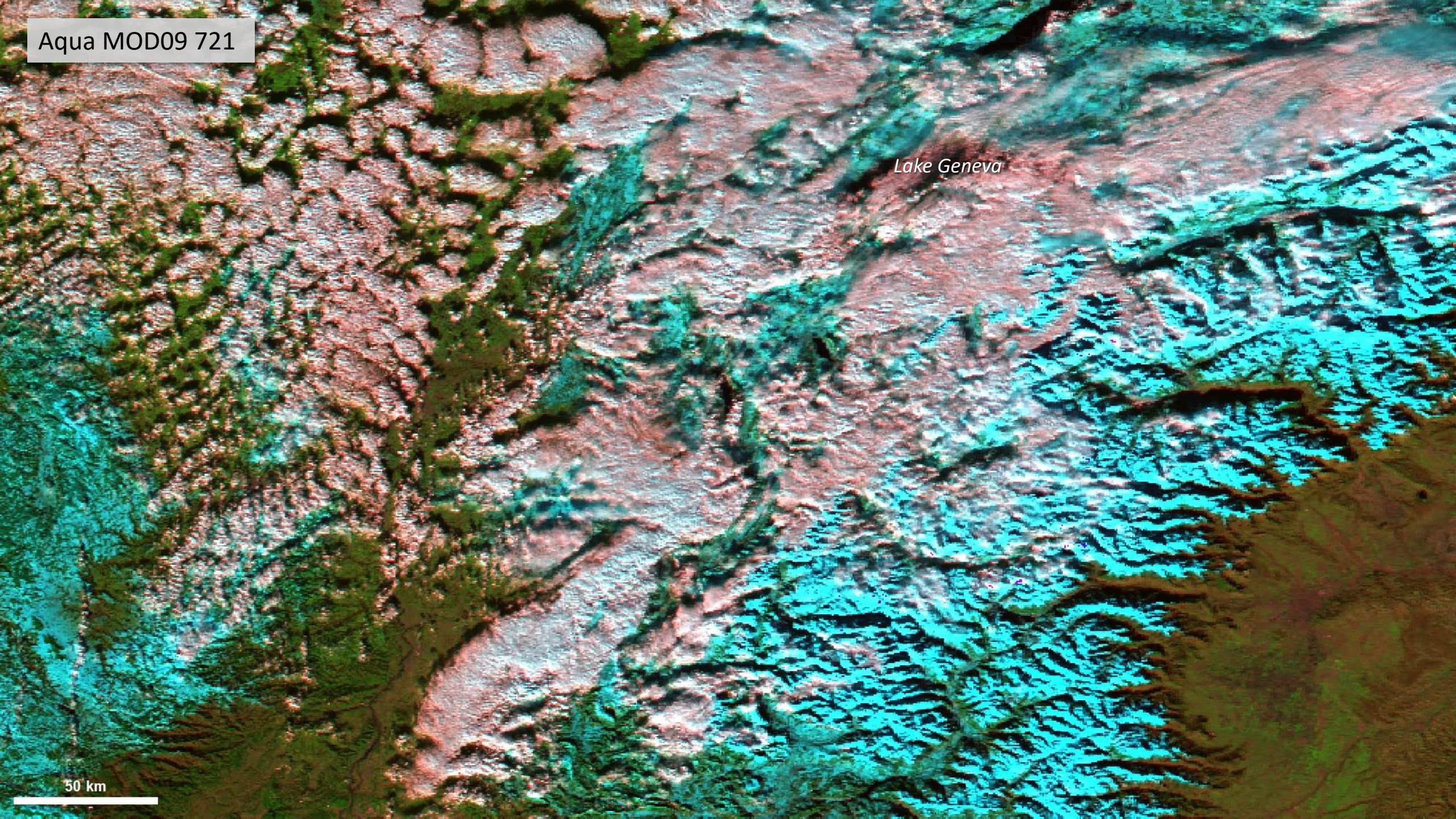
50 km



Aqua MOD09 721

Lake Geneva

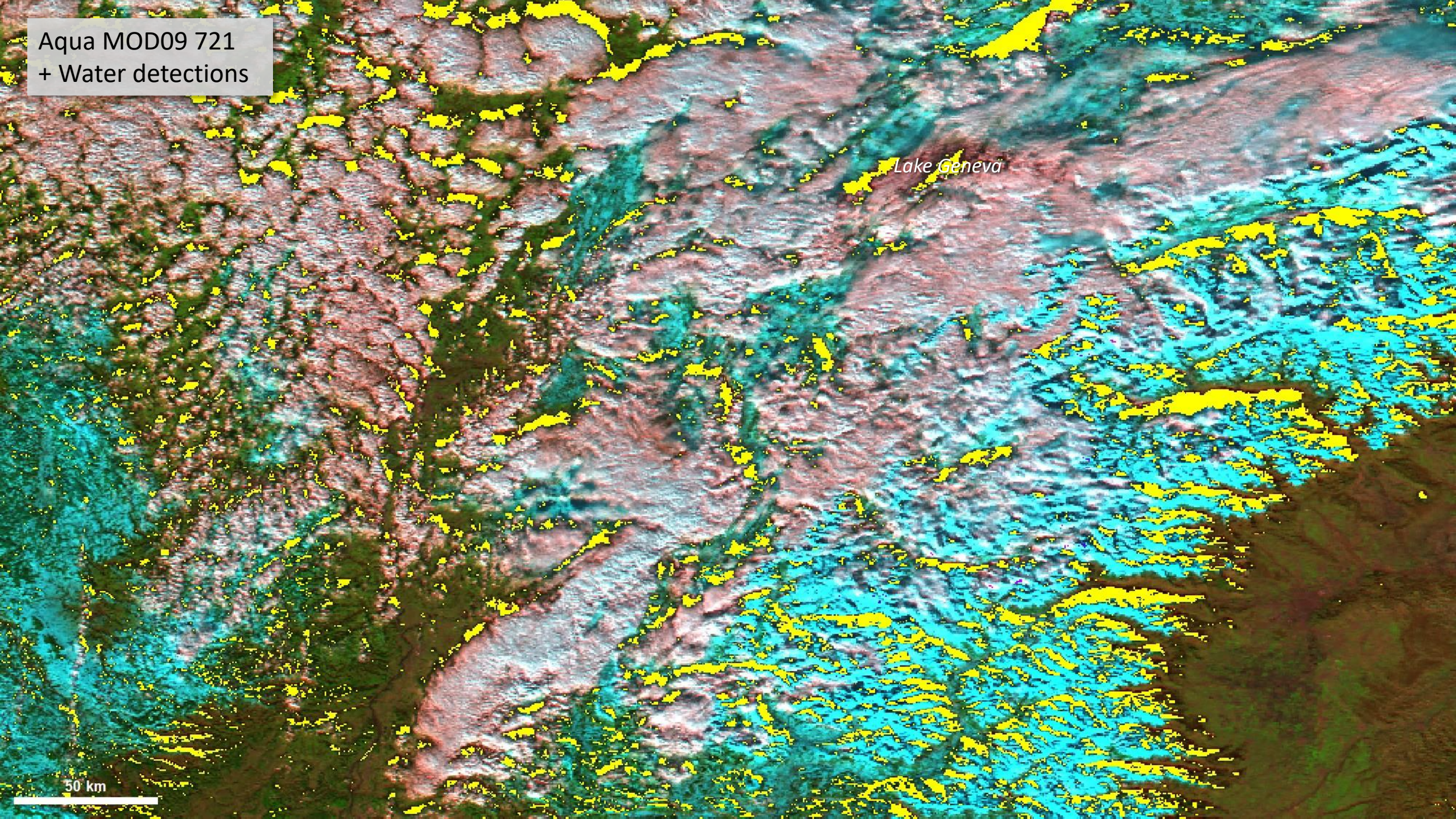
50 km



Aqua MOD09 721
+ Water detections

Lake Geneva

50 km



Aqua MOD09 721

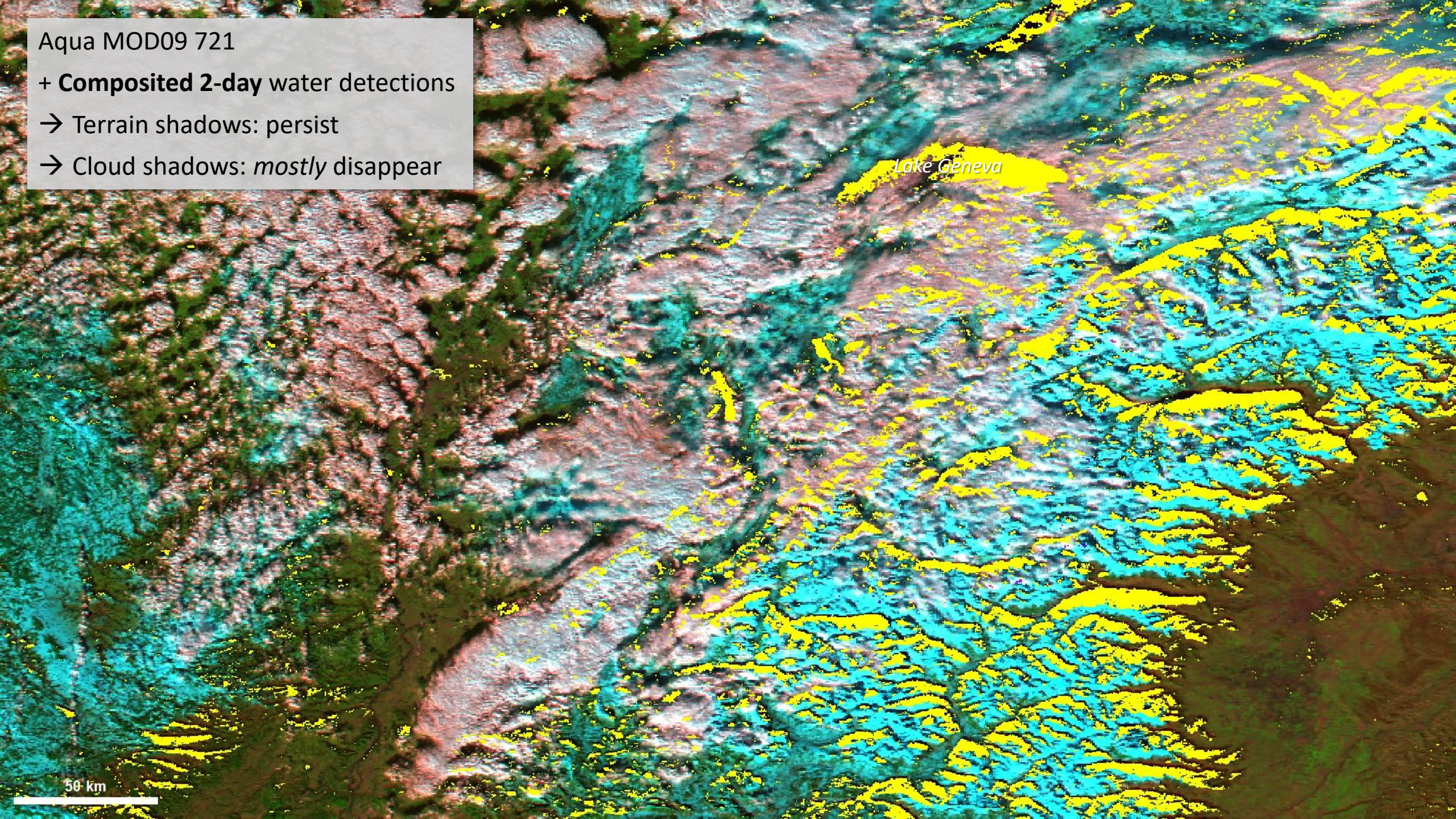
+ **Composited 2-day** water detections

→ Terrain shadows: persist

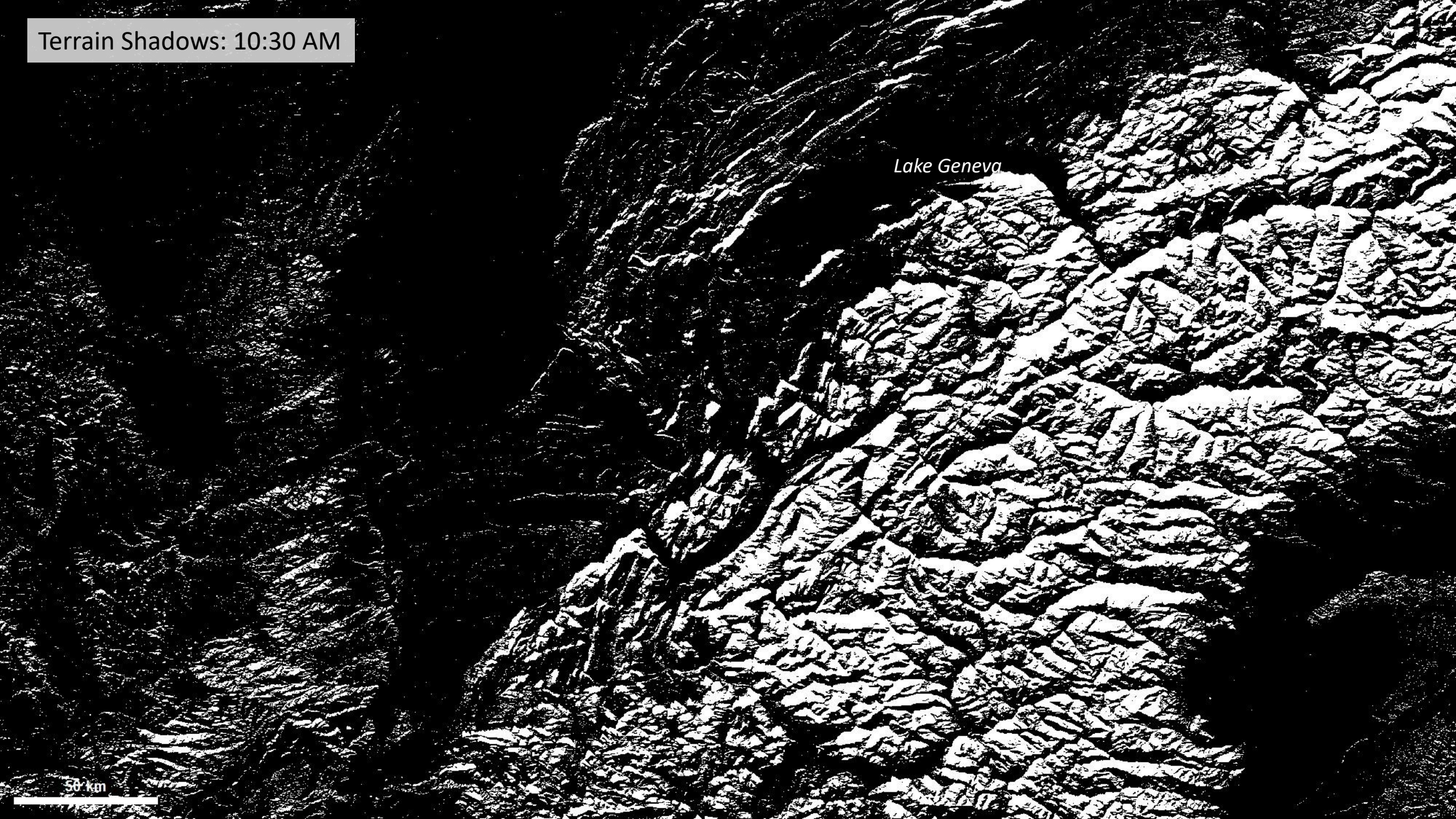
→ Cloud shadows: *mostly* disappear

Lake Geneva

50 km



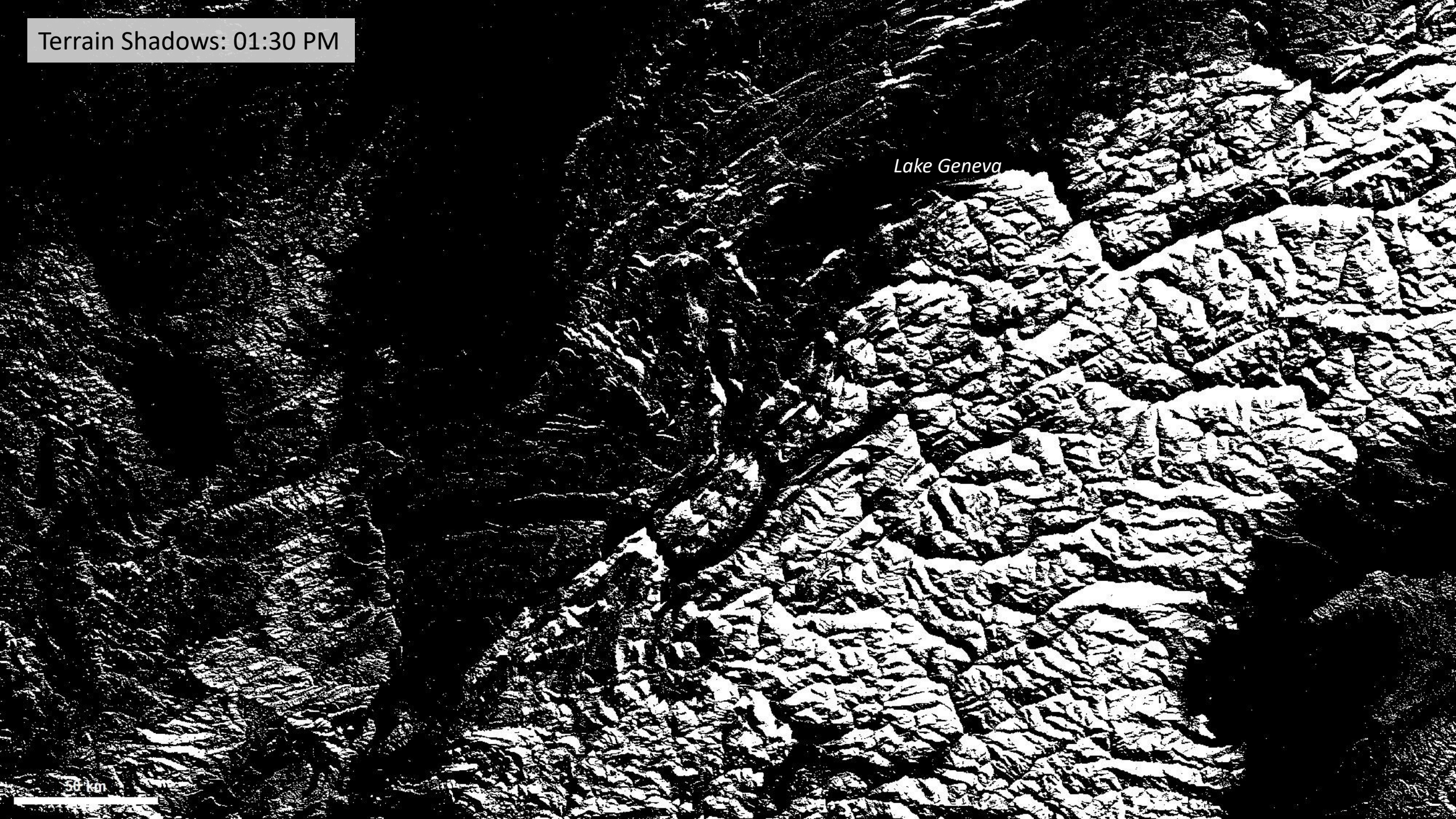
Terrain Shadows: 10:30 AM



Terrain Shadows: 01:30 PM

Lake Geneva

50 km



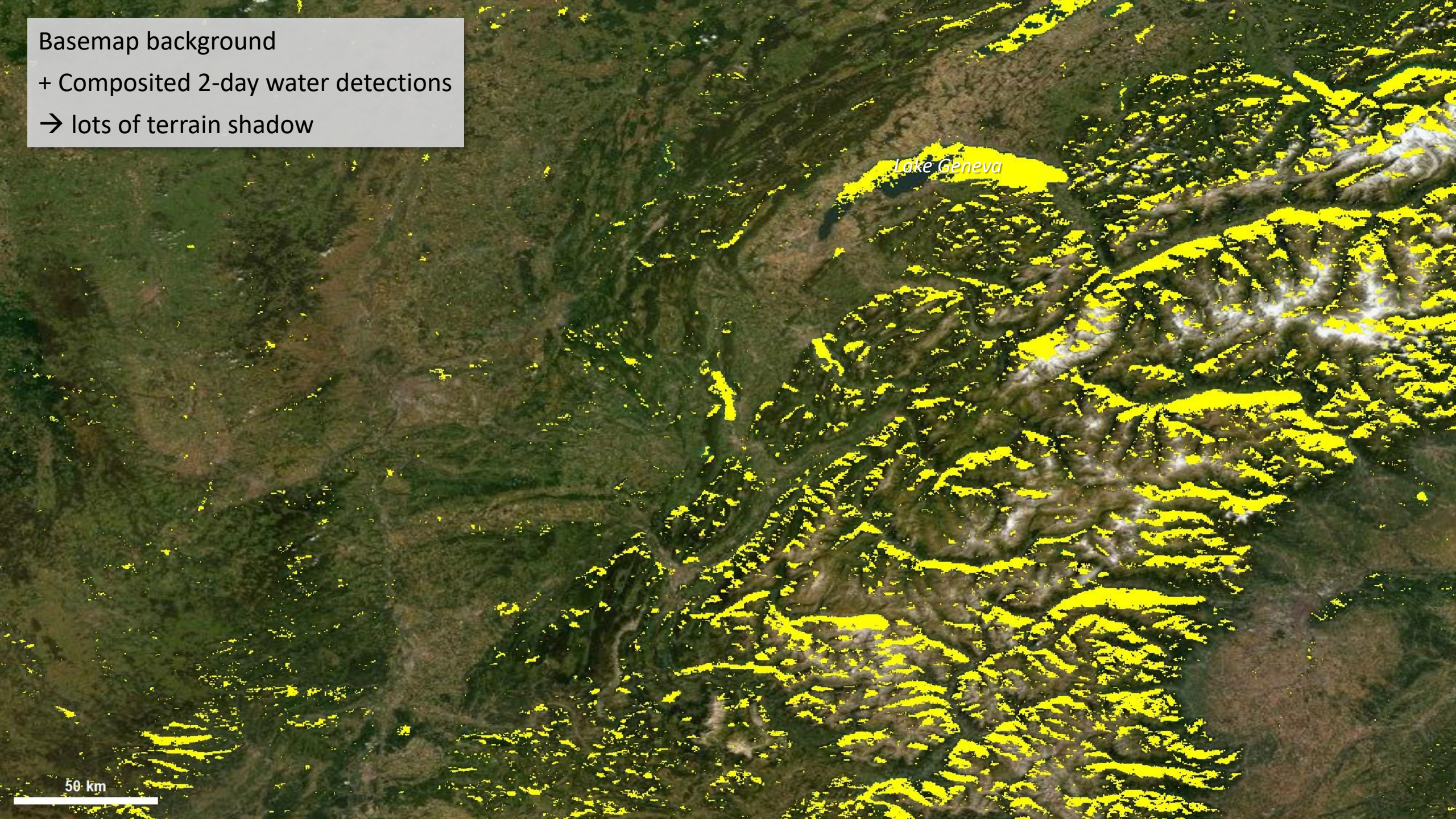
Basemap background

+ Composited 2-day water detections

→ lots of terrain shadow

Lake Geneva

50 km



Basemap background

+ Composited 2-day water detections

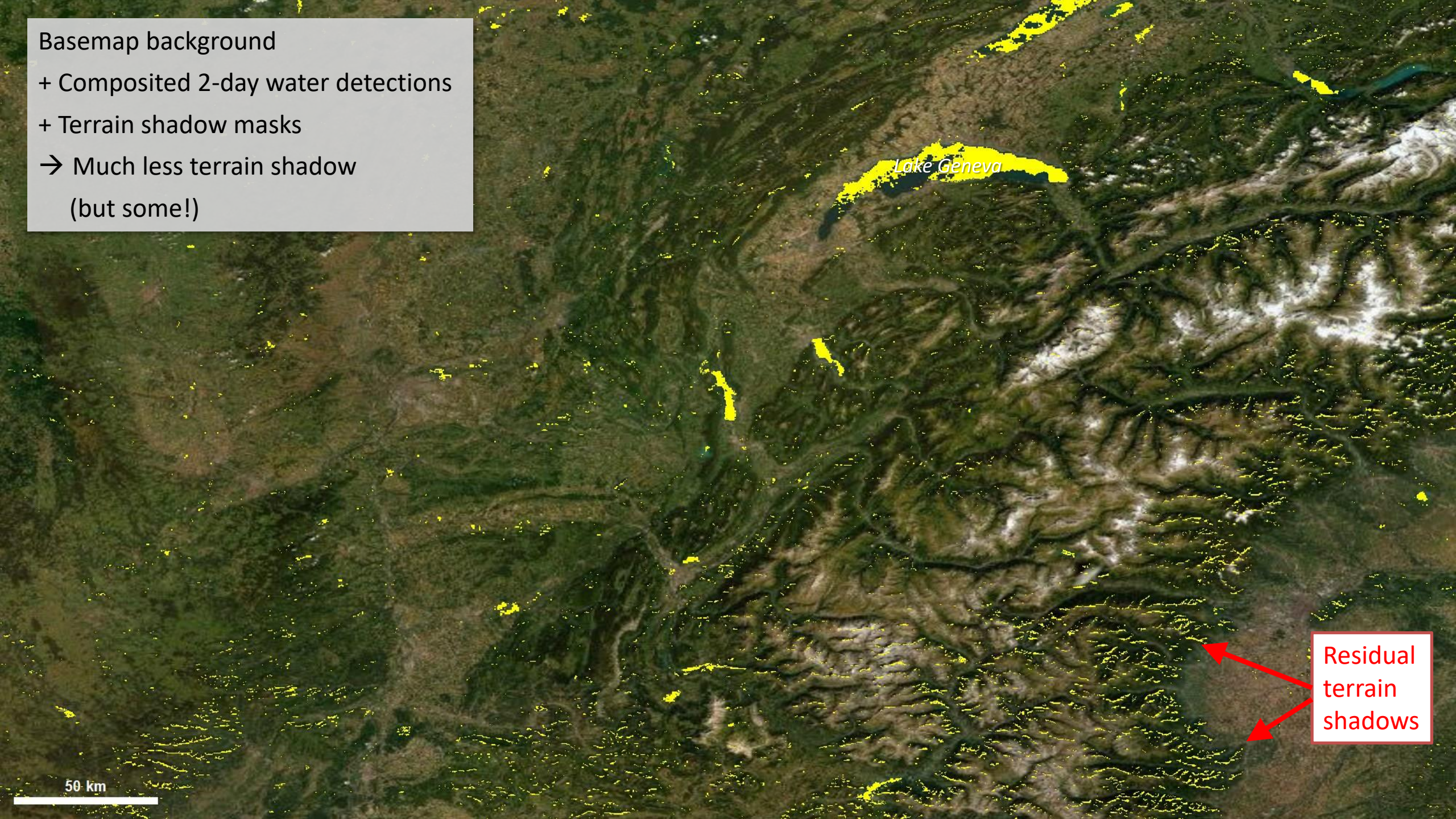
+ Terrain shadow masks

→ Much less terrain shadow
(but some!)

Lake Geneva

Residual
terrain
shadows

50 km

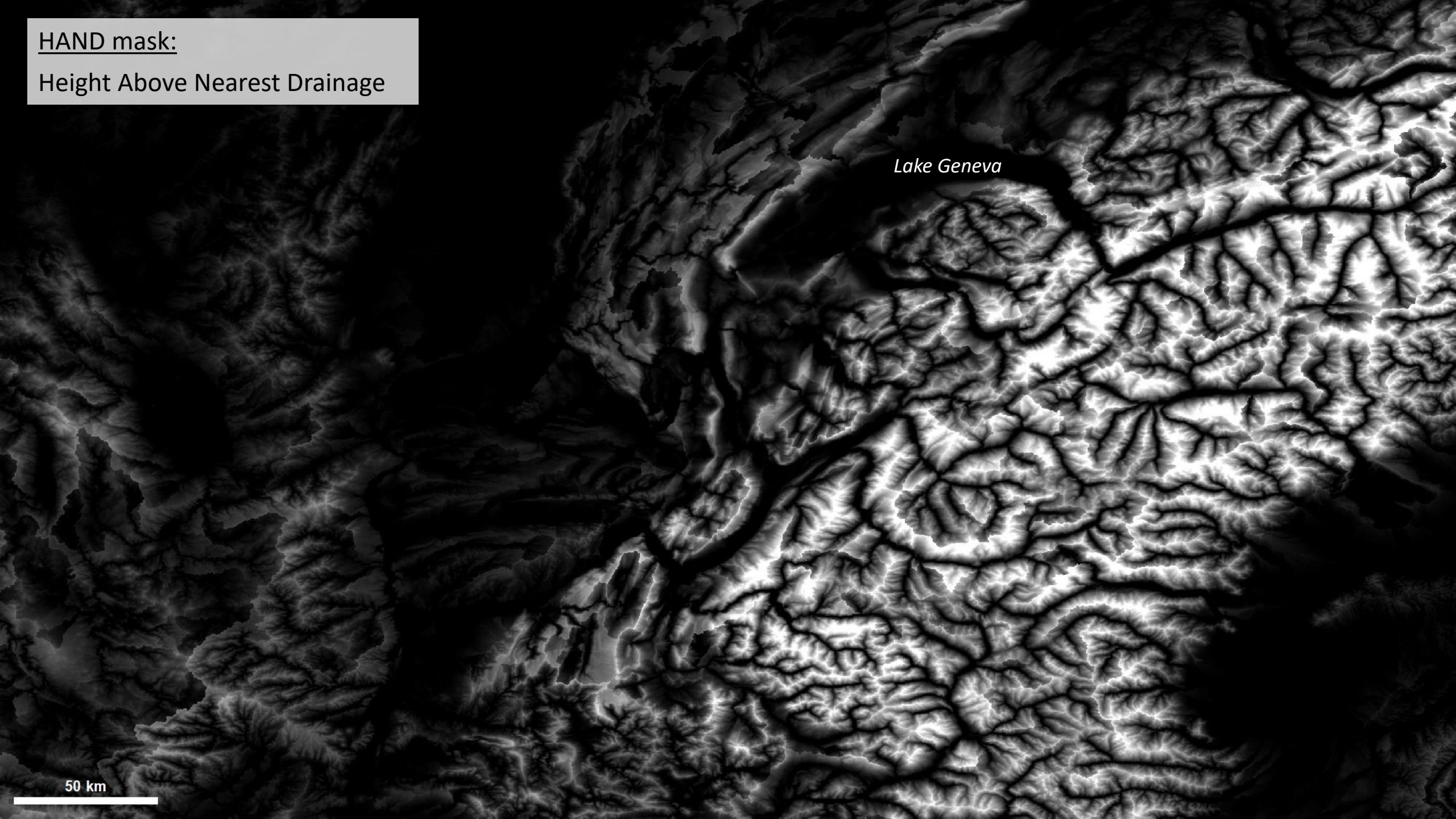


HAND mask:

Height Above Nearest Drainage

Lake Geneva

50 km

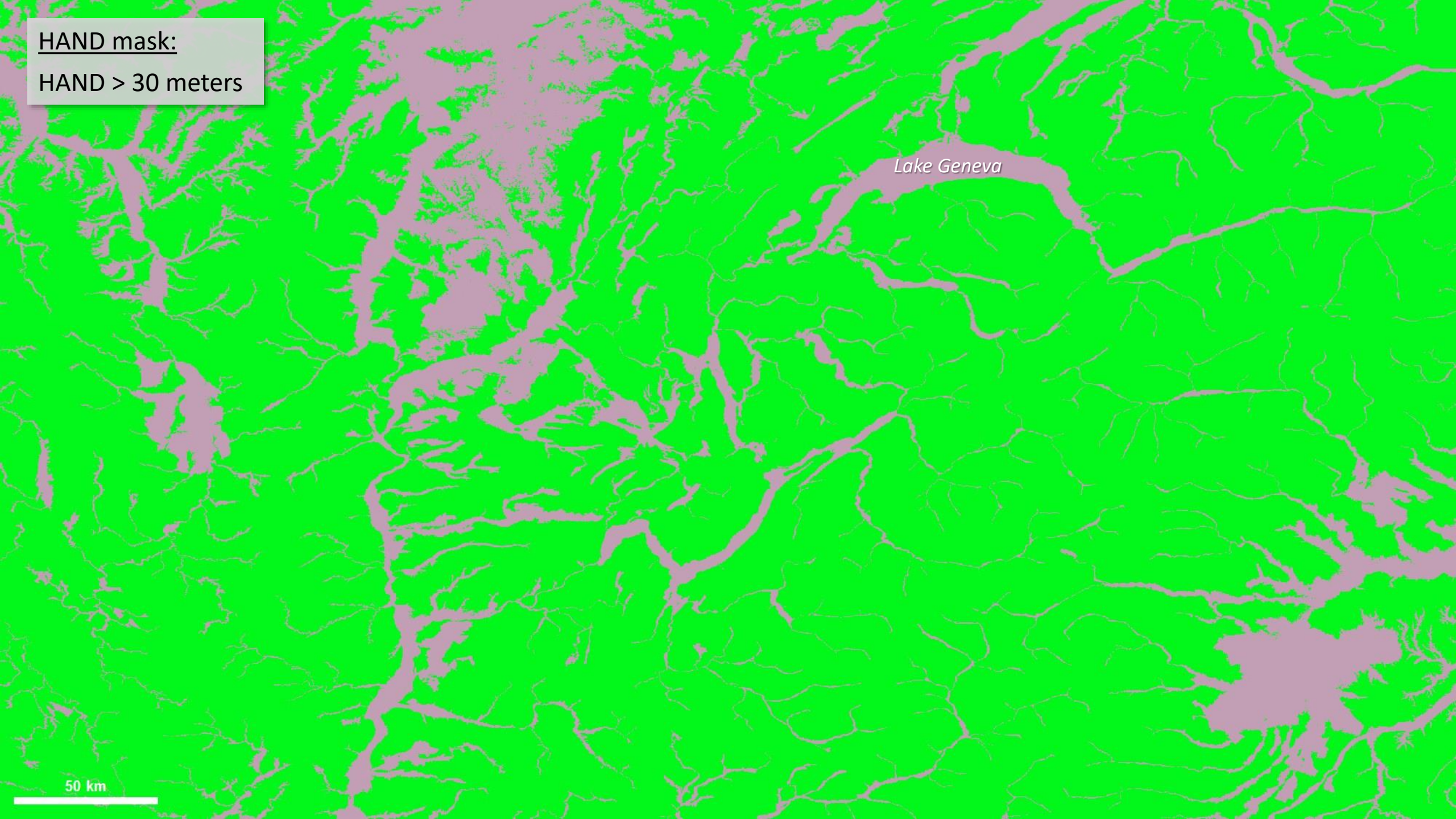


HAND mask:

HAND > 30 meters

Lake Geneva

50 km



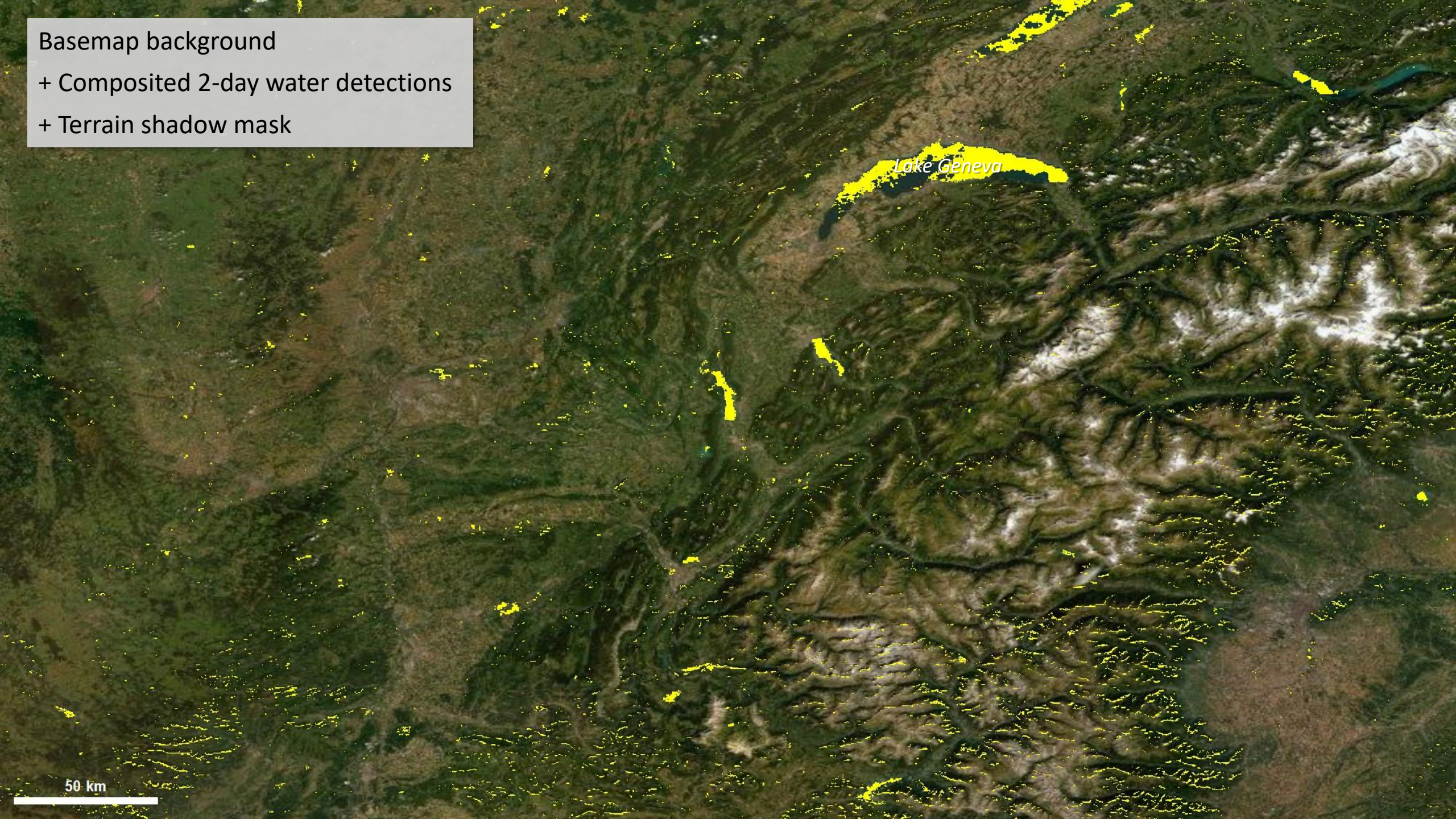
Basemap background

+ Composited 2-day water detections

+ Terrain shadow mask

Lake Geneva

50 km



Basemap background

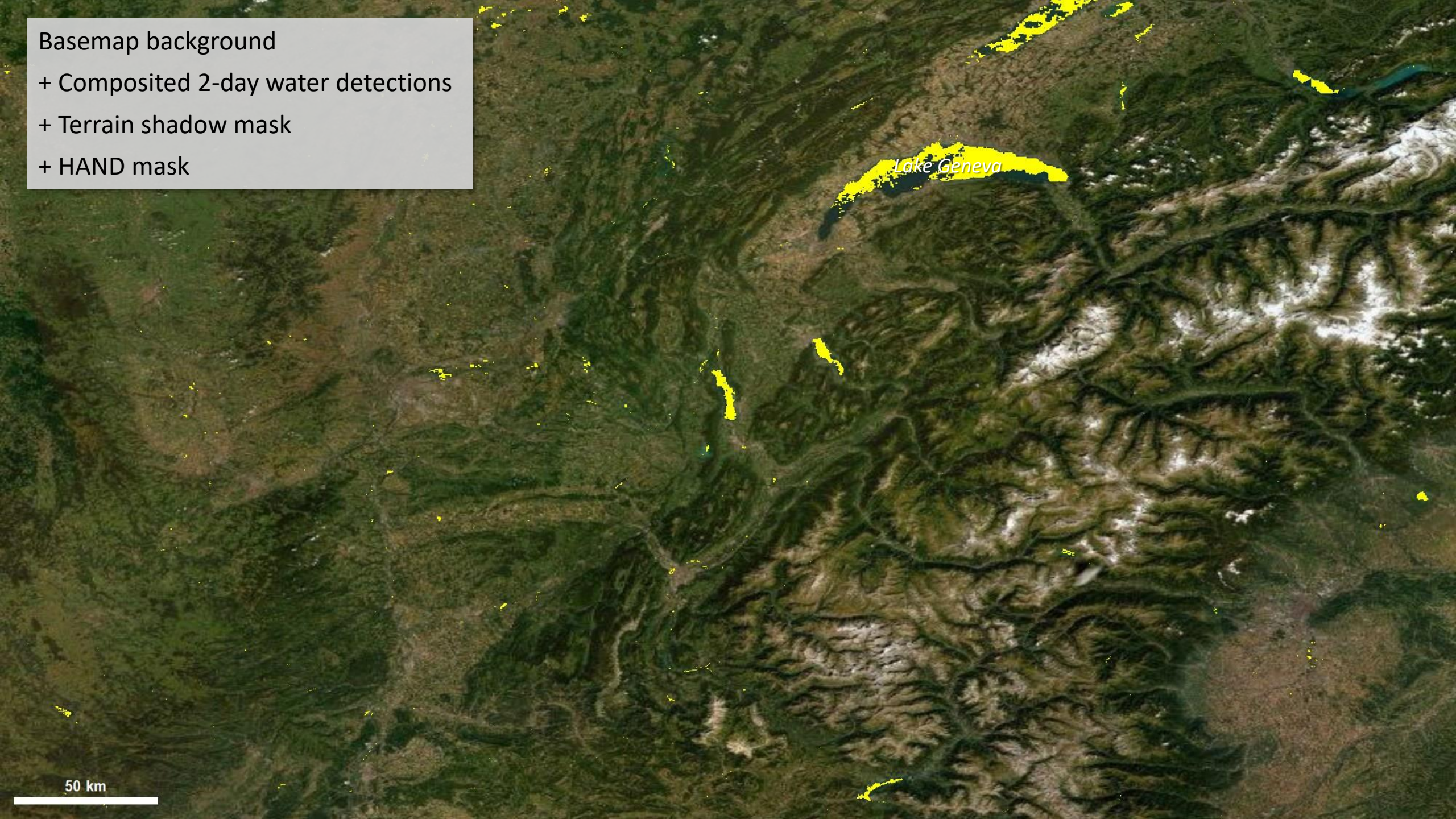
+ Composited 2-day water detections

+ Terrain shadow mask

+ HAND mask

Lake Geneva

50 km

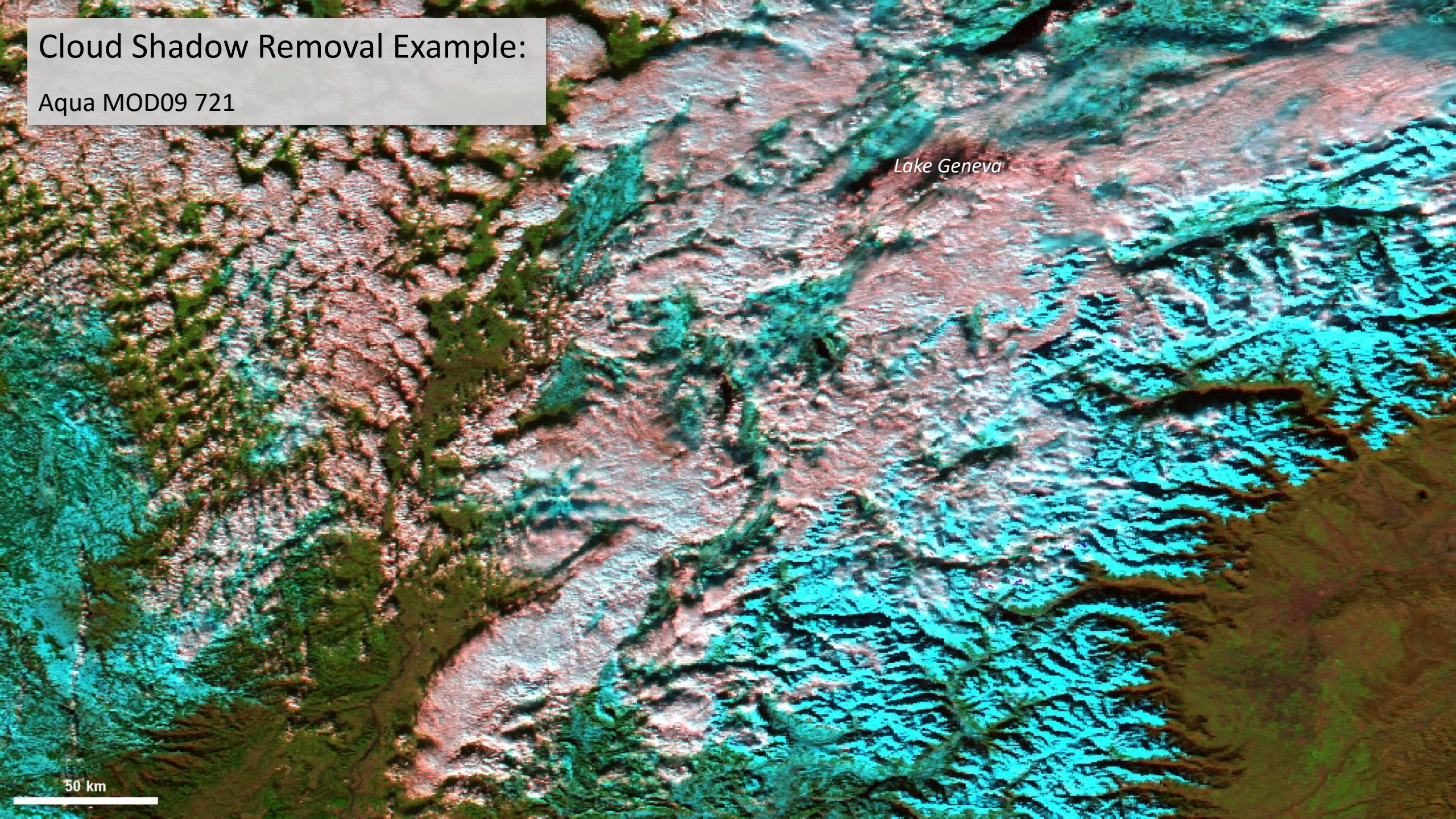


Cloud Shadow Removal Example:

Aqua MOD09 721

Lake Geneva

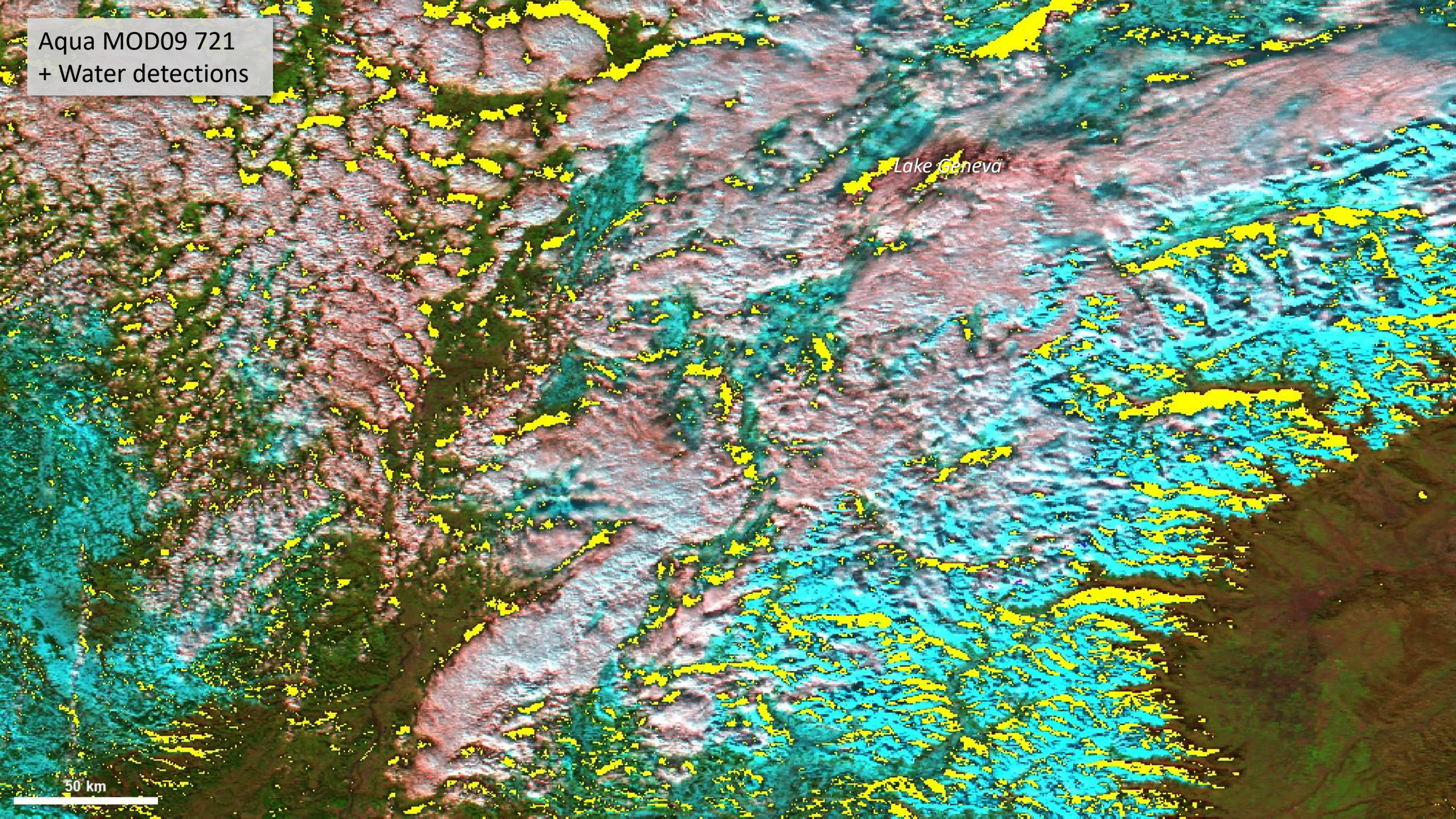
50 km



Aqua MOD09 721
+ Water detections

Lake Geneva

50 km



Aqua MOD09 721

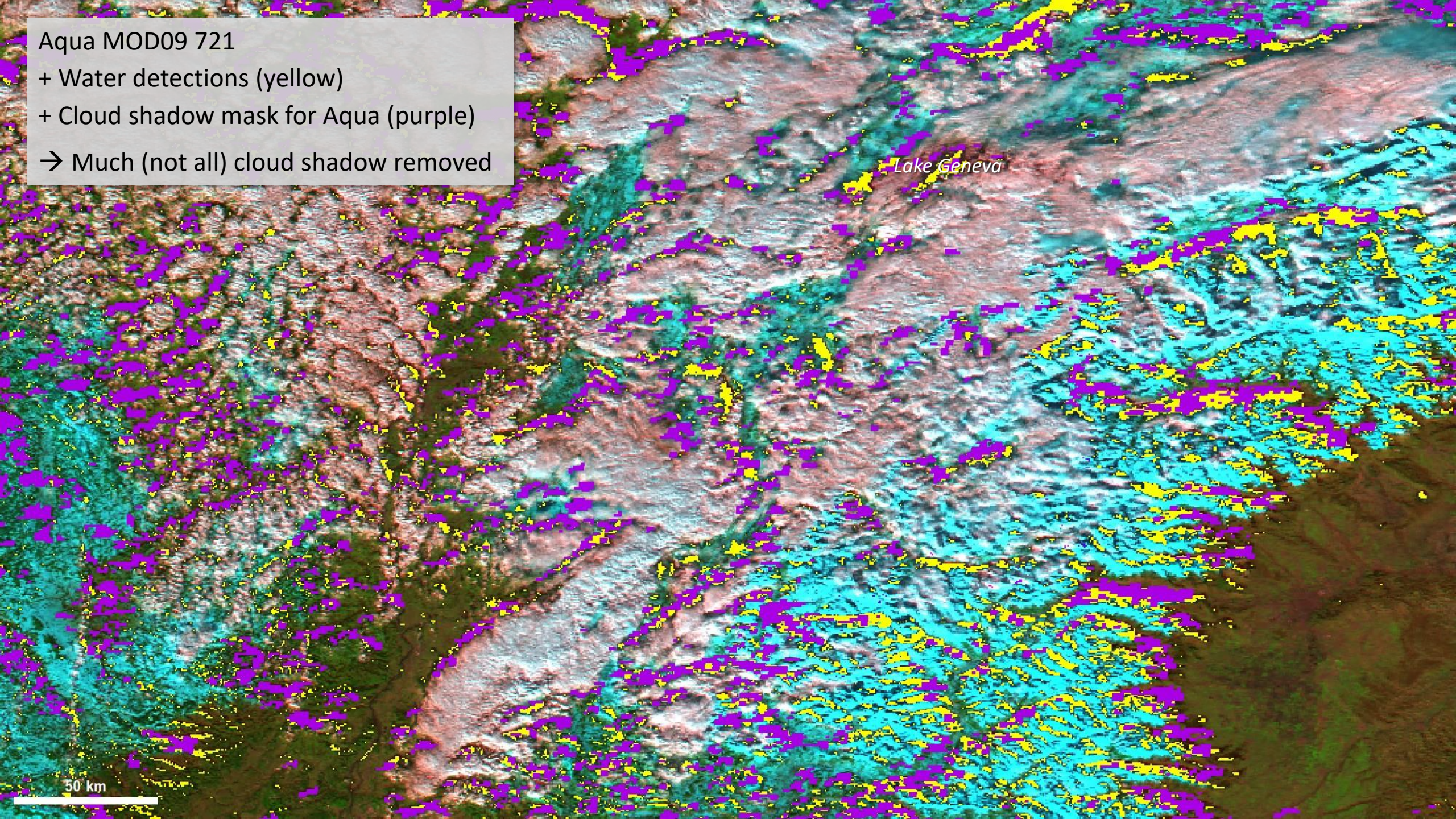
+ Water detections (yellow)

+ Cloud shadow mask for Aqua (purple)

→ Much (not all) cloud shadow removed

Lake Geneva

50 km



4. Determination of “flood”

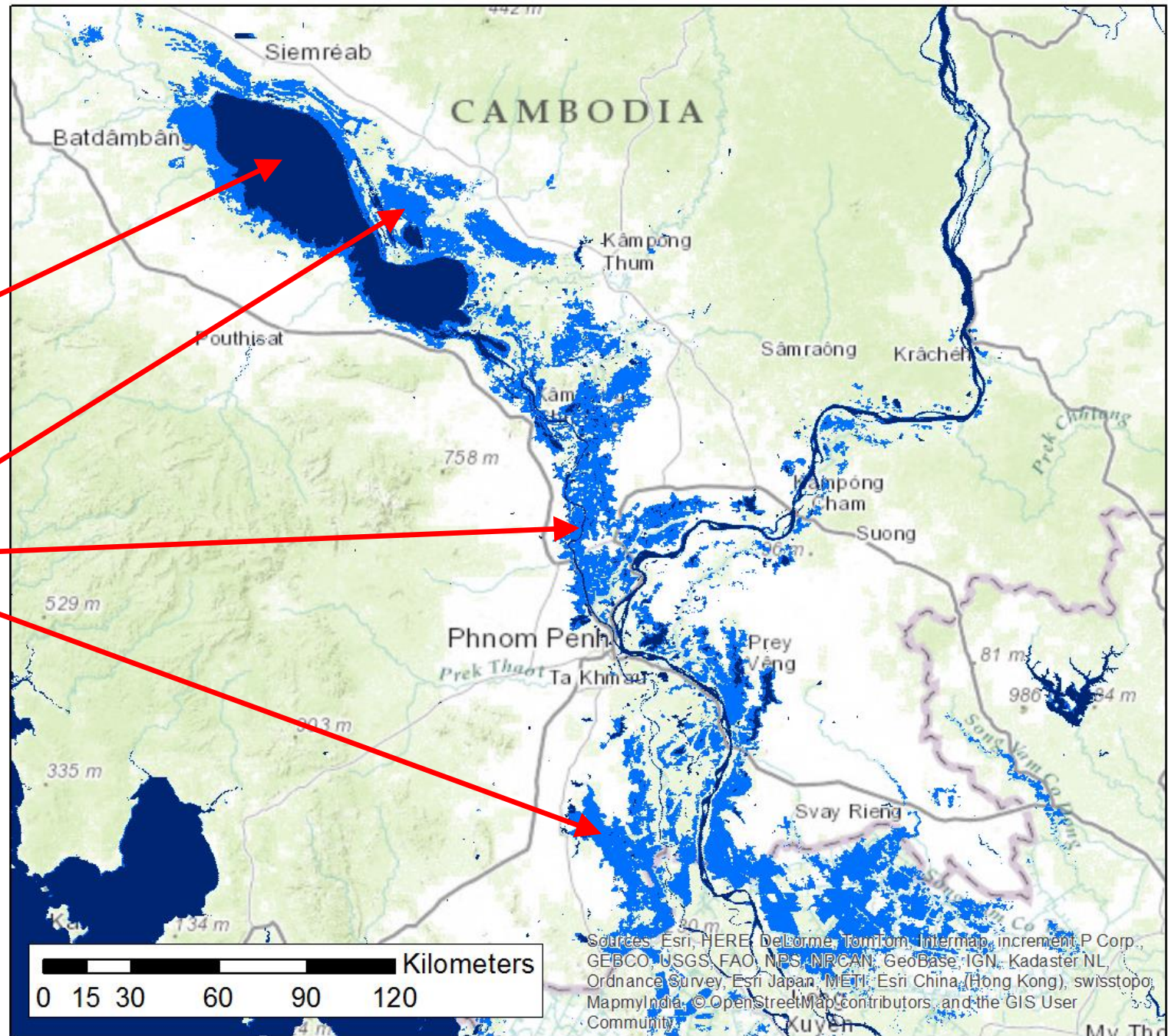
- Compare detected to “reference water” = expected water
- Pre-LANCE: MOD44W static global water product
- LANCE: plan to generate our own from the flood product
 - Can be more easily updated to reflect real surface water changes
 - Pending backprocessing (after LANCE NRT processing operational)
 - Interim: use our existing reference water (original MOD44W)
- New Feature: “Recurring flood”
 - Using product archive, can identify regions with regular flooding
 - Will be marked differently in flood product: “recurring flood”

Example: (Cambodia)

Permanent water vs recurring flooding

Reference water

Recurring flood

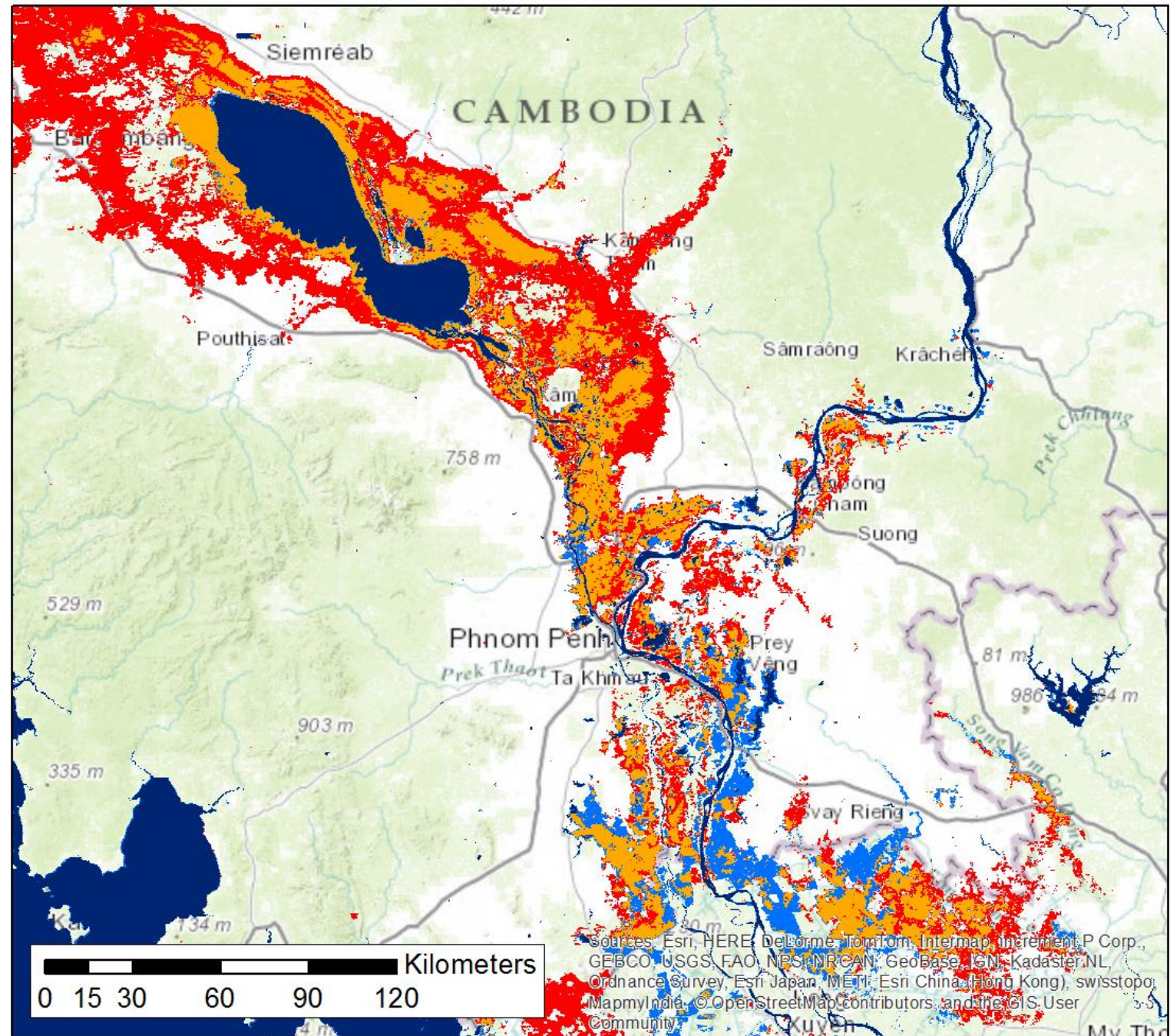


Example: (Cambodia)

Applied to Oct 2013 flood product

Differentiates:

- Recurring flood (orange)
- Flood (red)



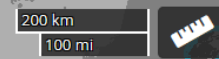
(11-Oct-2013, 2-day product)

LANCE Improvements: ESDIS/Worldview browsing

<https://worldview.earthdata.nasa.gov>

- Seamless browsing across 10x10 degree product tiles
- Easily follow flood progression over time
- Compare to past events
- Check optical imagery for clouds (“Can I use the 1-day product?”)
 - Need to check **all** contributing imagery (Terra + Aqua over 1, 2, or 3 days)
 - Not difficult in Worldview

Flood product 2-day



22.1221°, 95.2734° EPSG:4326

2019 NOV 06

1 DAY

◀ ▶

📹

SEP 2019

OCT 2019

NOV 2019

DEC 2019

JAN 2020

DAY

⏮ ⏭ ⏪ ⏩ ⏴ ⏵

 **WORLDVIEW**


 Layers

 Events

 Data



OVERLAYS

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 Coastlines
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BASE LAYERS

 Corrected Reflectance (True Color)
Suomi NPP / VIIRS

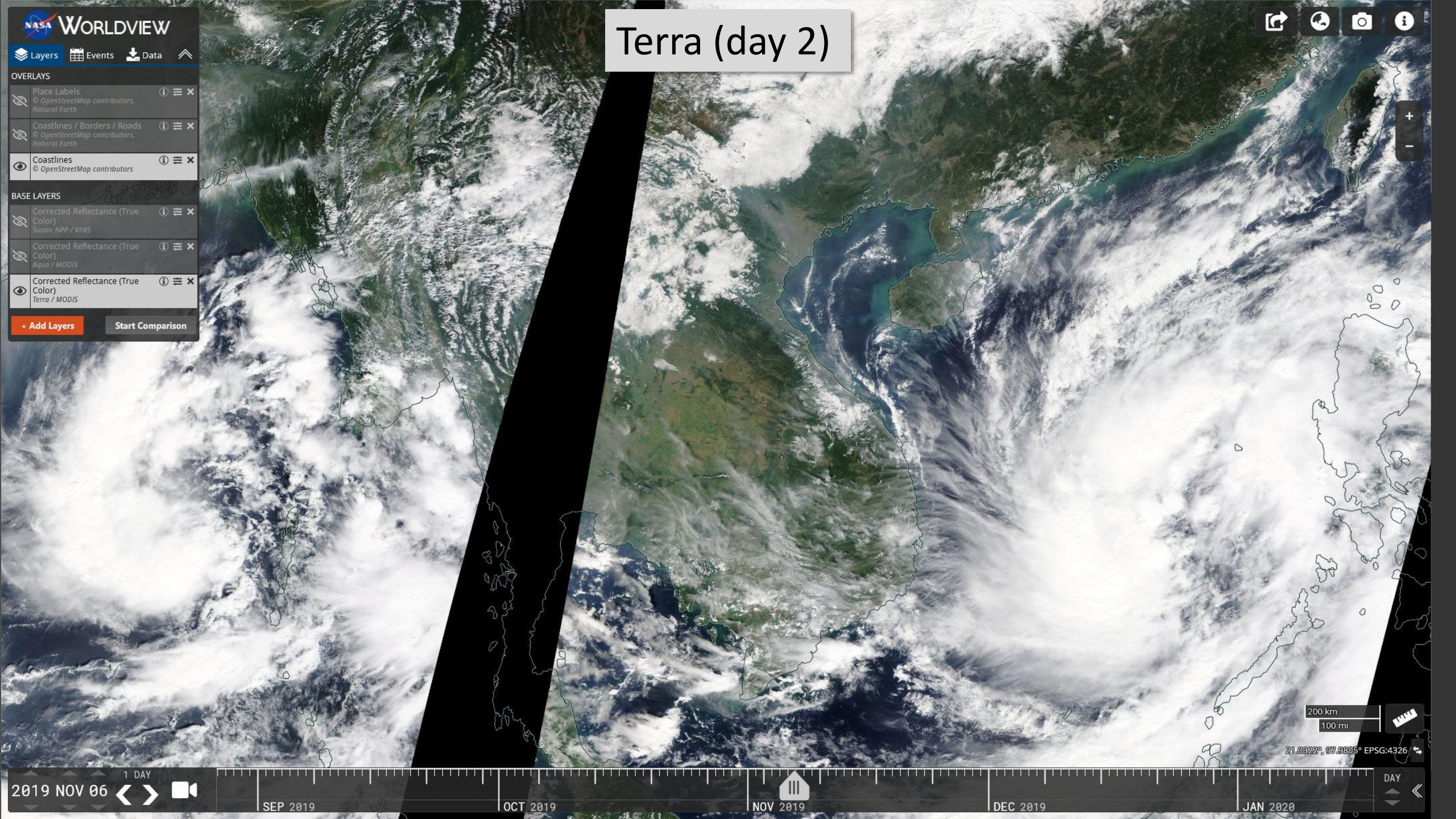
 Corrected Reflectance (True Color)
Aqua / MODIS

 Corrected Reflectance (True Color)
Terra / MODIS

+ Add Layers

Start Comparison

Terra (day 2)



200 km
100 mi



21.0322°, 97.9805° EPSG:4326

1 DAY

2019 NOV 06



SEP 2019

OCT 2019

NOV 2019

DEC 2019

JAN 2020

DAY

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Natural Earth
- Coastlines
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BASE LAYERS


- Corrected Reflectance (True Color)
Suomi NPP / VIIRS
- Corrected Reflectance (True Color)
Aqua / MODIS
- Corrected Reflectance (True Color)
Terra / MODIS

+ Add Layers Start Comparison

Aqua (day 2)

+
-

200 km
100 mi
25.0928°, 93.1465° EPSG:4326


 **WORLDVIEW**


Layers


Events

Data


OVERLAYS


 Place Labels
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BASE LAYERS

 Corrected Reflectance (True Color)
Suomi NPP / VIIRS

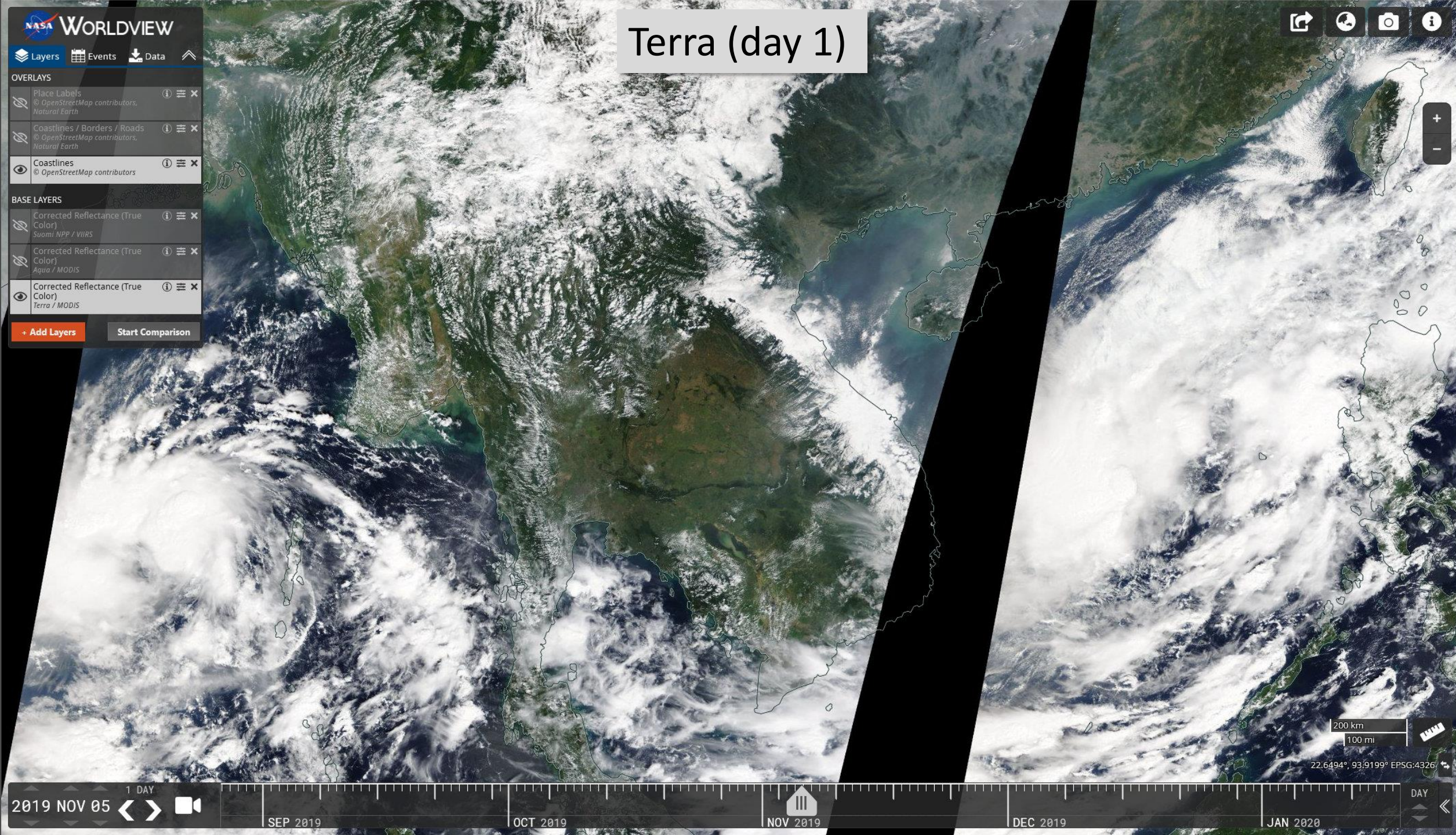
 Corrected Reflectance (True Color)
Aqua / MODIS

 Corrected Reflectance (True Color)
Terra / MODIS

+ Add Layers

Start Comparison

Terra (day 1)



Aqua (day 1)

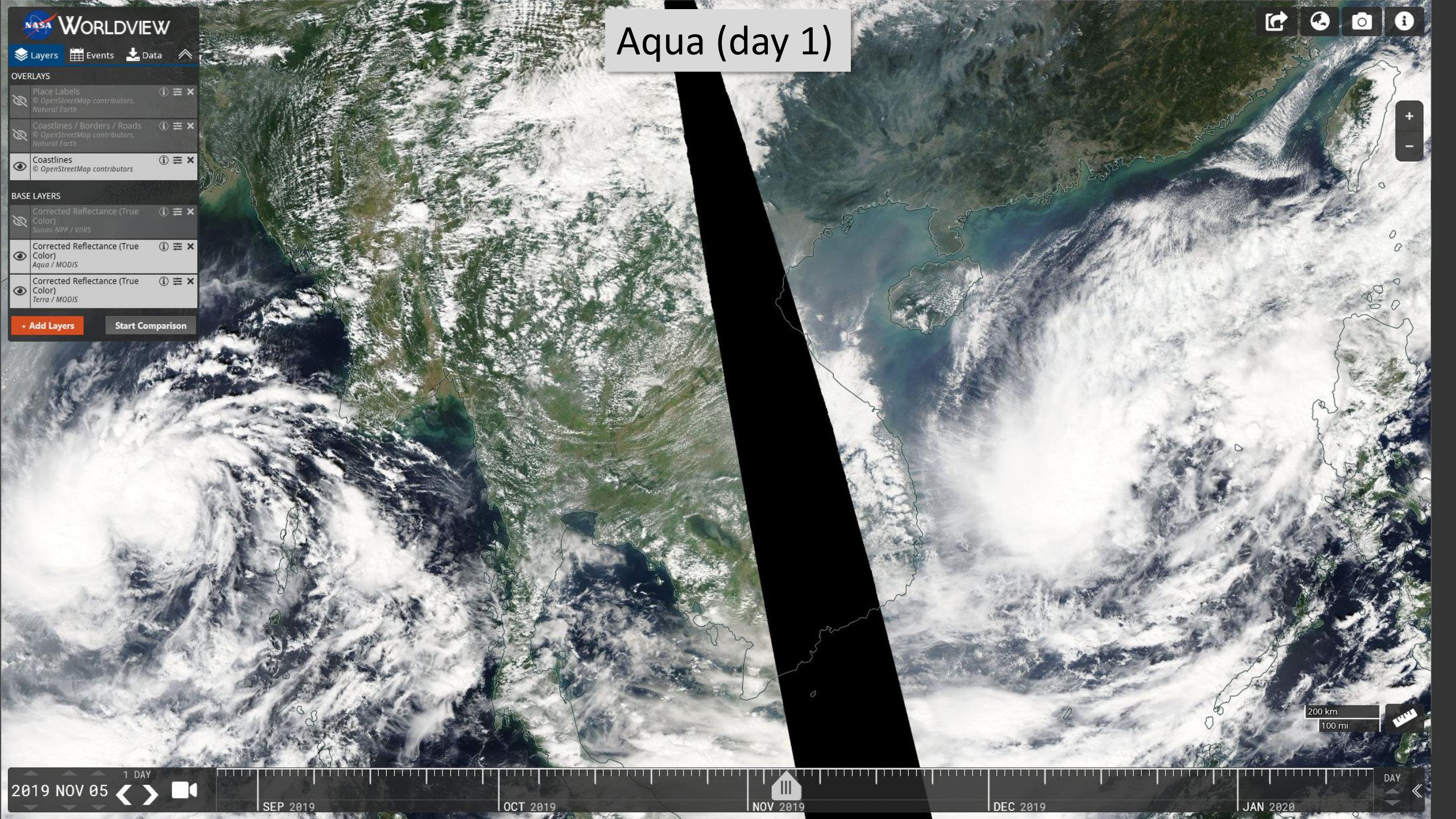
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Natural Earth
- Coastlines
© OpenStreetMap contributors

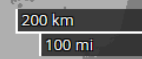
BASE LAYERS

- Corrected Reflectance (True Color)
Suomi NPP / VIIRS
- Corrected Reflectance (True Color)
Aqua / MODIS
- Corrected Reflectance (True Color)
Terra / MODIS

+ Add Layers Start Comparison



Flood product 2-day



22.1221°, 95.2734° EPSG:4326

2019 NOV 06

1 DAY

◀ ▶

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SEP 2019

OCT 2019

NOV 2019

DEC 2019

JAN 2020

DAY

⏮ ⏭

LANCE: Product changes

- Operating on swath granules vs pre-mosaicked tiles
 - Better cloud-shadow screening on 1-day products
 - Lower latency product delivery (as soon as Aqua data available)
 - 10 x 10 degree product tile updates as new swath granules available
- Adding “recurring flood”
- Adding global generation of 1-day product
- Discontinuing generation of 14-day product
- Distribution format changes
- Distribution website change

Changes in output data values

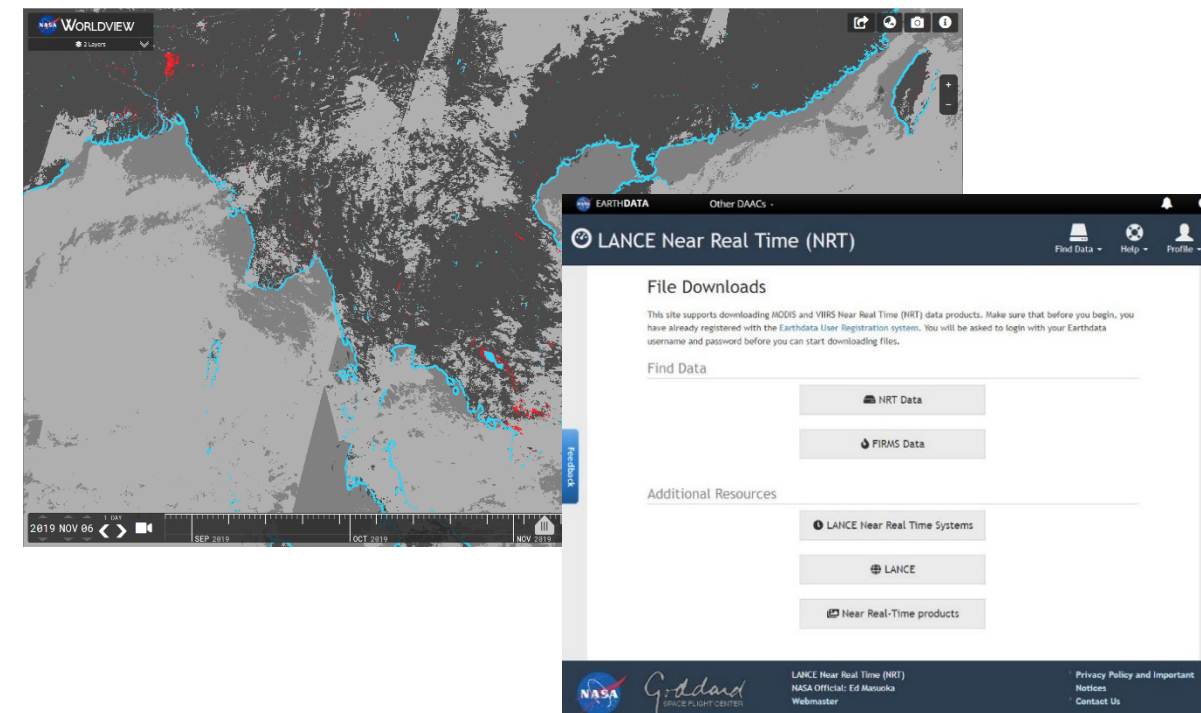
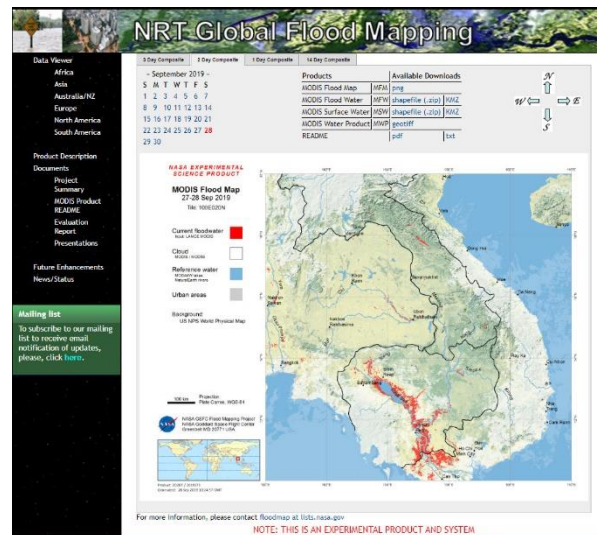
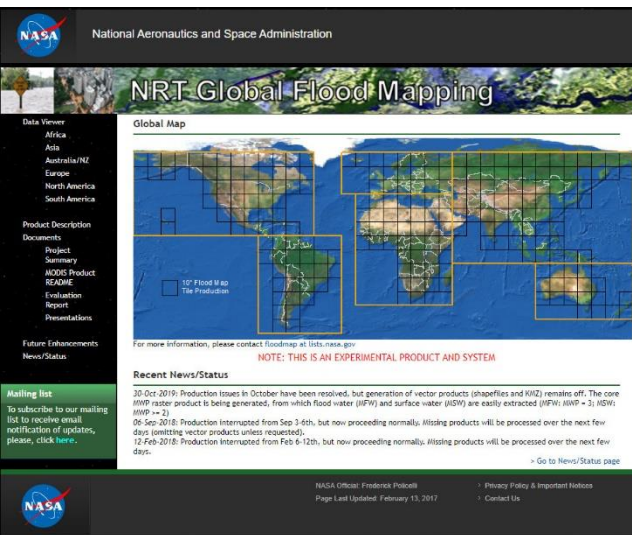
	Pre-LANCE	LANCE
Insufficient data	0	255
No water detected	1	0
Permanent water	2	1
Recurring flood	NA	2
Flood	3	3

Changes in output format

- Pre-LANCE current product
 - 1 geotiff file for each 1-day, 2-day, and 3-day product (per $10^{\circ} \times 10^{\circ}$ tile)
 - Previously: shapefile and KMZ (Google Earth) formats
- LANCE product
 - 1 HDF file per tile per day, containing all products (1-day, 2-day, and 3-day)
 - No vector products planned
 - Possibly geotiffs
 - Raw water detections per swath granule available as Level-2 product

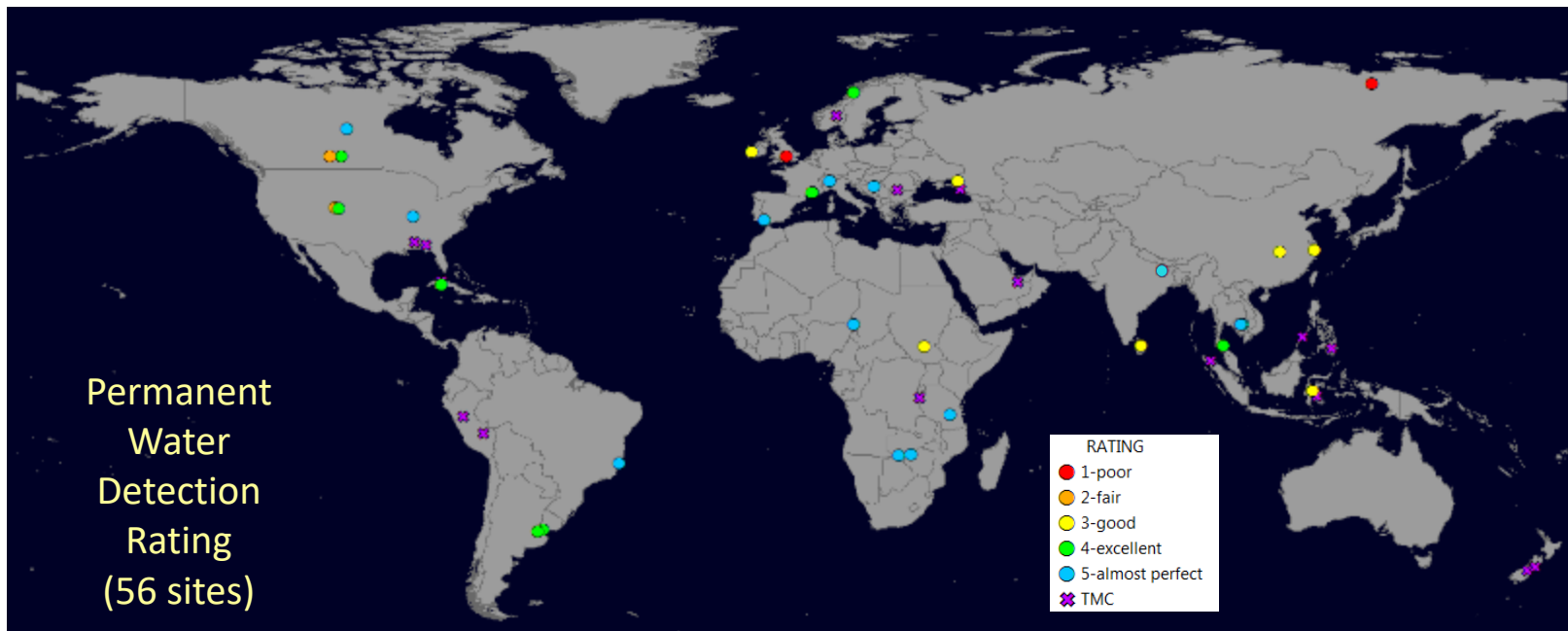
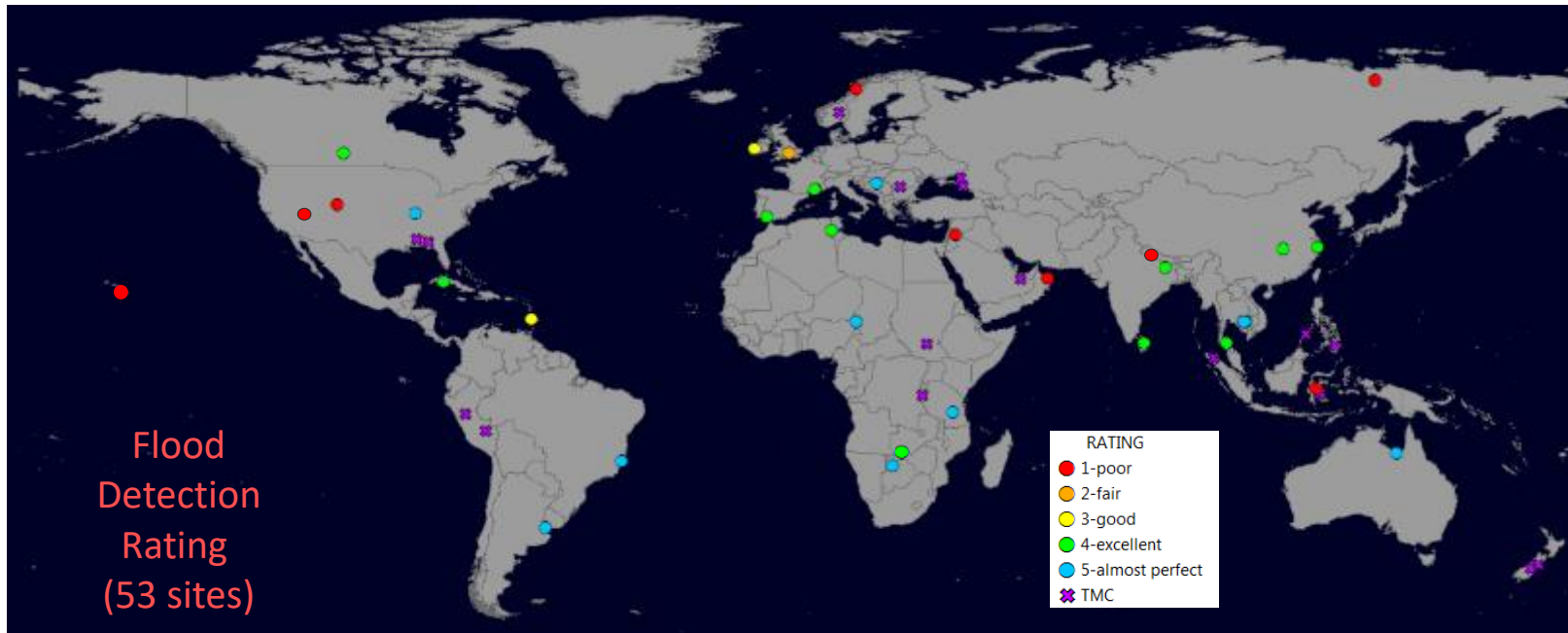
Changes in delivery

- Pre-LANCE (current)
 - Website with clickable map and reduced-resolution graphic previews
 - No easy method to download many files
- LANCE
 - Worldview browsable map
 - Standard LANCE NRT access:
<https://nrt3.modaps.eosdis.nasa.gov>



Validation

- Purpose:
 - Is water detection algorithm correctly detecting water that is visibly obvious? Are certain situations problematic?
 - Do we see differences between detection of flood vs normal water?
- Method:
 - Manual qualitative assessment, using raw MODIS or Landsat imagery to inform.
 - Ground truth is difficult to find, expensive to collect, and generally biased towards accessible locations.
 - Flood events selected from DFO master list of recent floods
 - Global distribution.
 - Including areas with high and low cloud cover (humid tropics to arid regions).
 - Varying landcovers.



Flood Detection Ratings

RATING	Count	%
5-almost perfect	11	21
4-excellent	10	19
3-good	2	4
2-fair	1	2
1-poor	11	21
TMC - too many clouds	17	33
TOTAL	53	100

} 66% of clear

Permanent Water Detection Ratings

RATING	Count	%
5-almost perfect	15	28
4-excellent	9	17
3-good	7	13
2-fair	2	4
1-poor	4	8
TMC - too many clouds	16	30
TOTAL	54	100

} 84% of clear

Correct flood and permanent water identification

Brazil: 02 January 2014



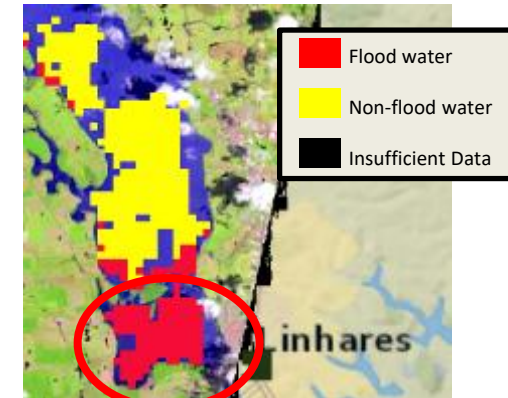
Base map



Landsat 8 Pre-flood
Apr 21, 2013



Landsat 8 Flood
Jan 2, 2014

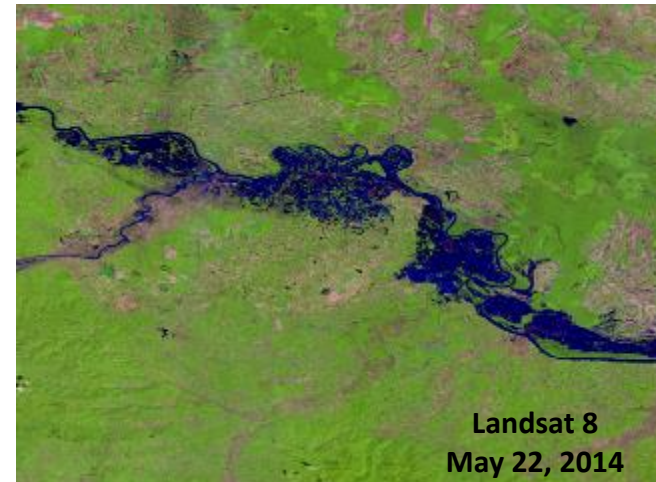


MODIS NRT product
Jan 3, 2014

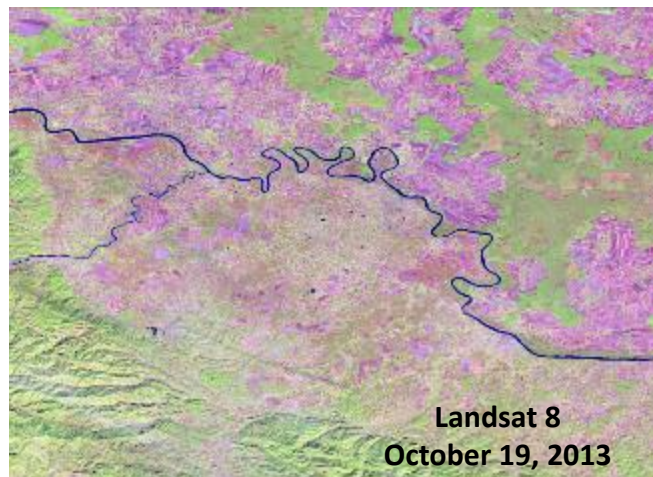
Sava river / Bosnia and Herzegovina:
23 May 2014



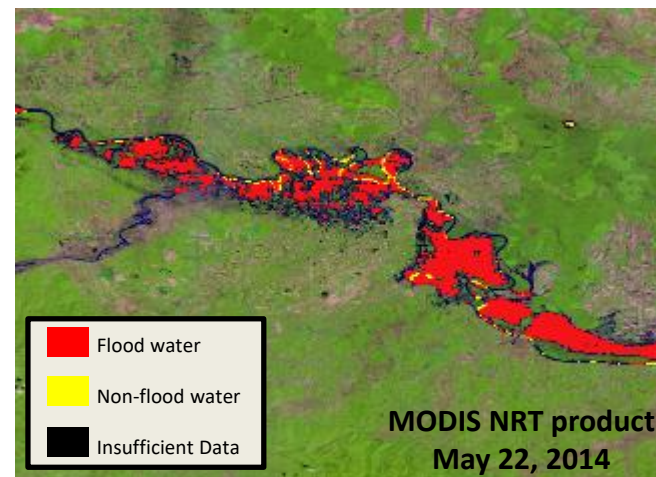
Base map



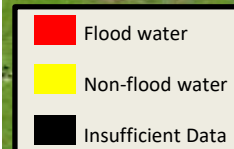
Landsat 8
May 22, 2014



Landsat 8
October 19, 2013



MODIS NRT product
May 22, 2014



Correct flood identification

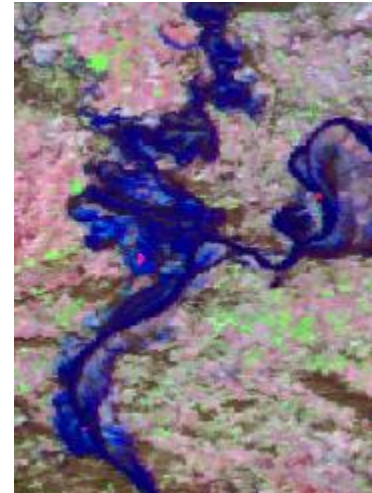
Mississippi (KY/IN/IL):
04 Jan 2014



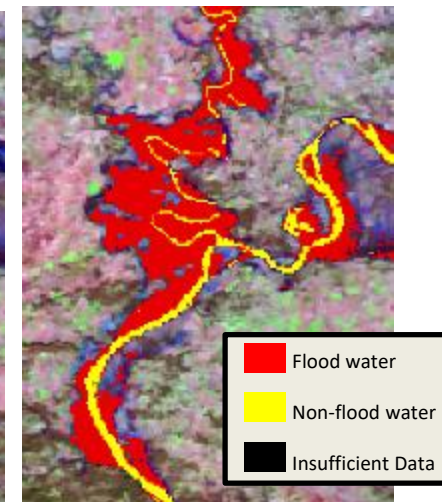
Base map



MODIS (MOD09) Pre-Flood
Oct 12, 2013



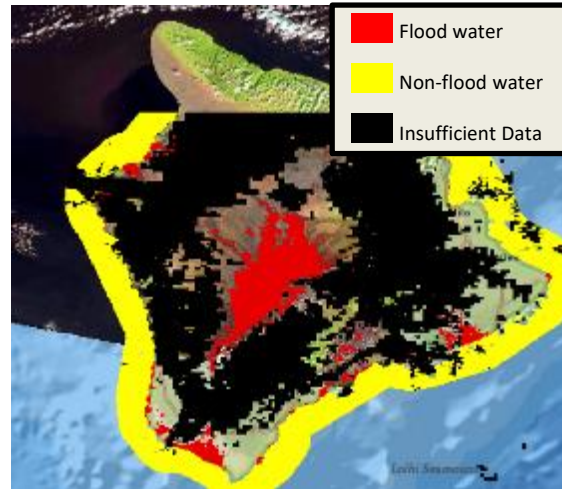
MODIS (MOD09) Flood
Jan 4, 2014



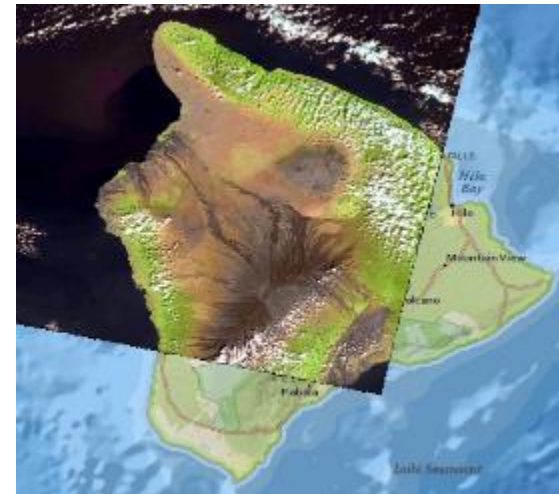
MODIS NRT Product
Jan 4, 2013

Barren rock / volcanic false positives

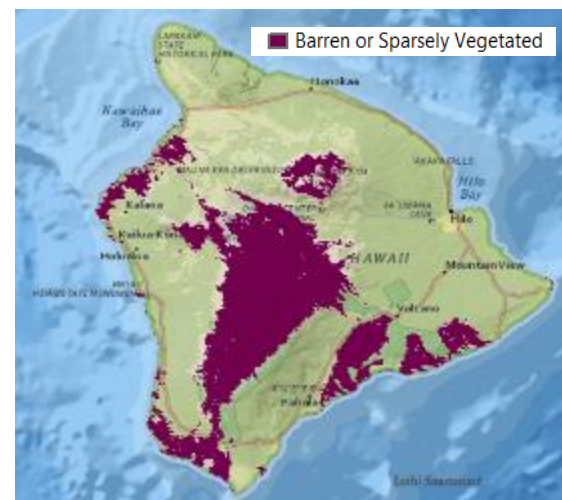
Mauna Loa, **Hawaii**: 17 Dec 2013



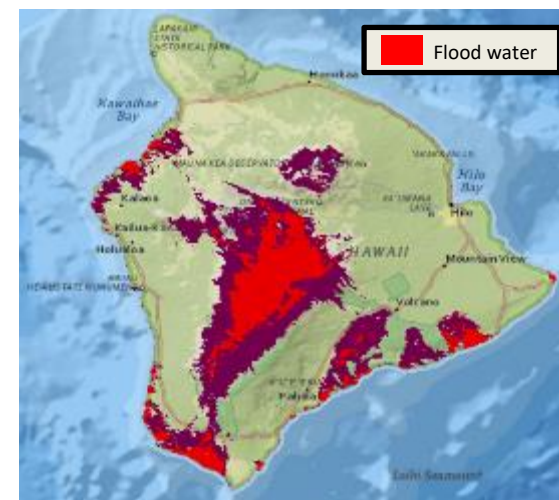
MODIS NRT Product



Landsat 8



MODIS (MCD12Q1) IGBP Land Cover



MODIS IGBP Land Cover with flood water

Flood detection limitations

- Cloudiness
- Flood spatial extent
 - 250 m pixels
- Flood temporal extent
 - Flash floods / short duration on ground
- Landcover
 - Water under tree cover
 - Urban
 - Exposed volcanic rock

Future directions

- Backprocessing archive
 - Nearly 20-year history of large-scale surface water dynamics for much of globe!
- Add VIIRS
 - Only afternoon, but adds additional observations, removes swath gaps
 - Somewhat lower resolution (375 vs 250 m)
 - Will become critical when Aqua fails
- Improve terrain shadow masking
- Alert system

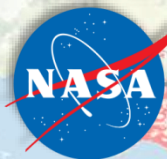
Potential Direct Readout Opportunities

- Use our products, customize for local case
 - Customized permanent and seasonal water layers to identify flood
 - Potentially have staff available to evaluate best product per event, and incorporate local maps and knowledge
- Generate products directly
 - Latency
 - Reduced further with direct broadcast.
 - Customize water detection algorithms
 - Optimize for local conditions / landcover



Thank you!

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Hydrology Laboratory
Goddard Space Flight Center



Dartmouth
Flood Observatory